

Plate motions from DORIS data

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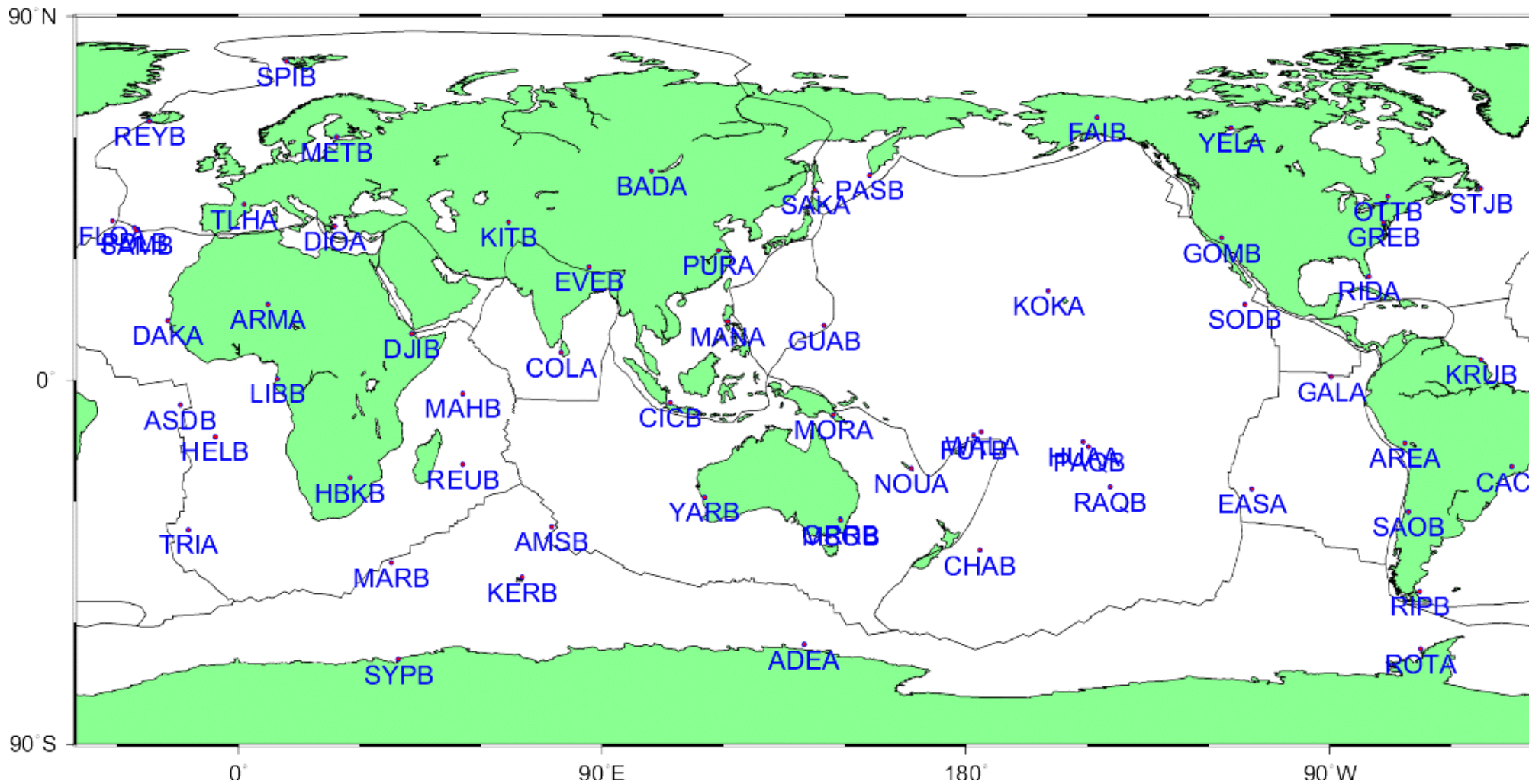
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² *CLS, Collecte Localisation Satellites, Ramonville, France*

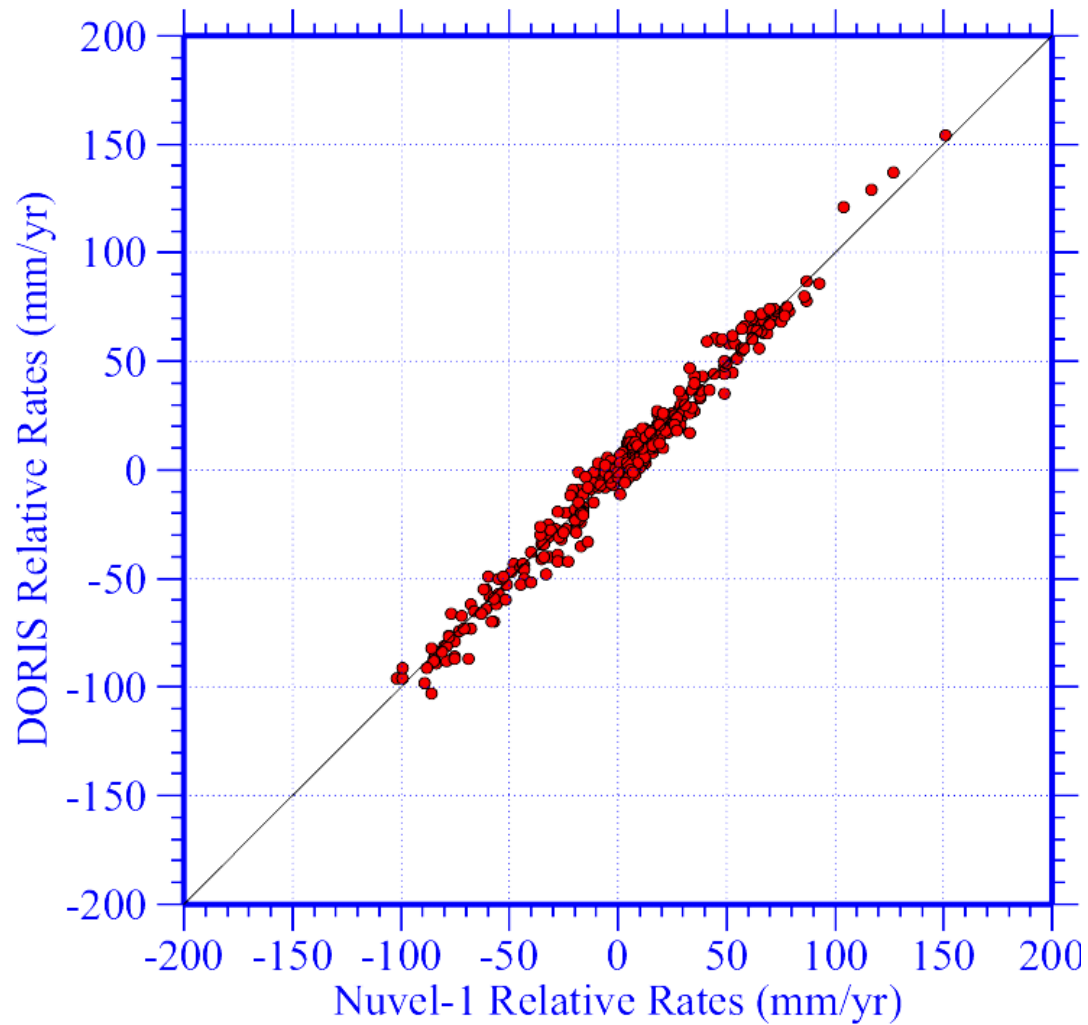
³ *LEGOS/GRGS (CNES/CNRS-UPS), Toulouse, France*



DORIS network

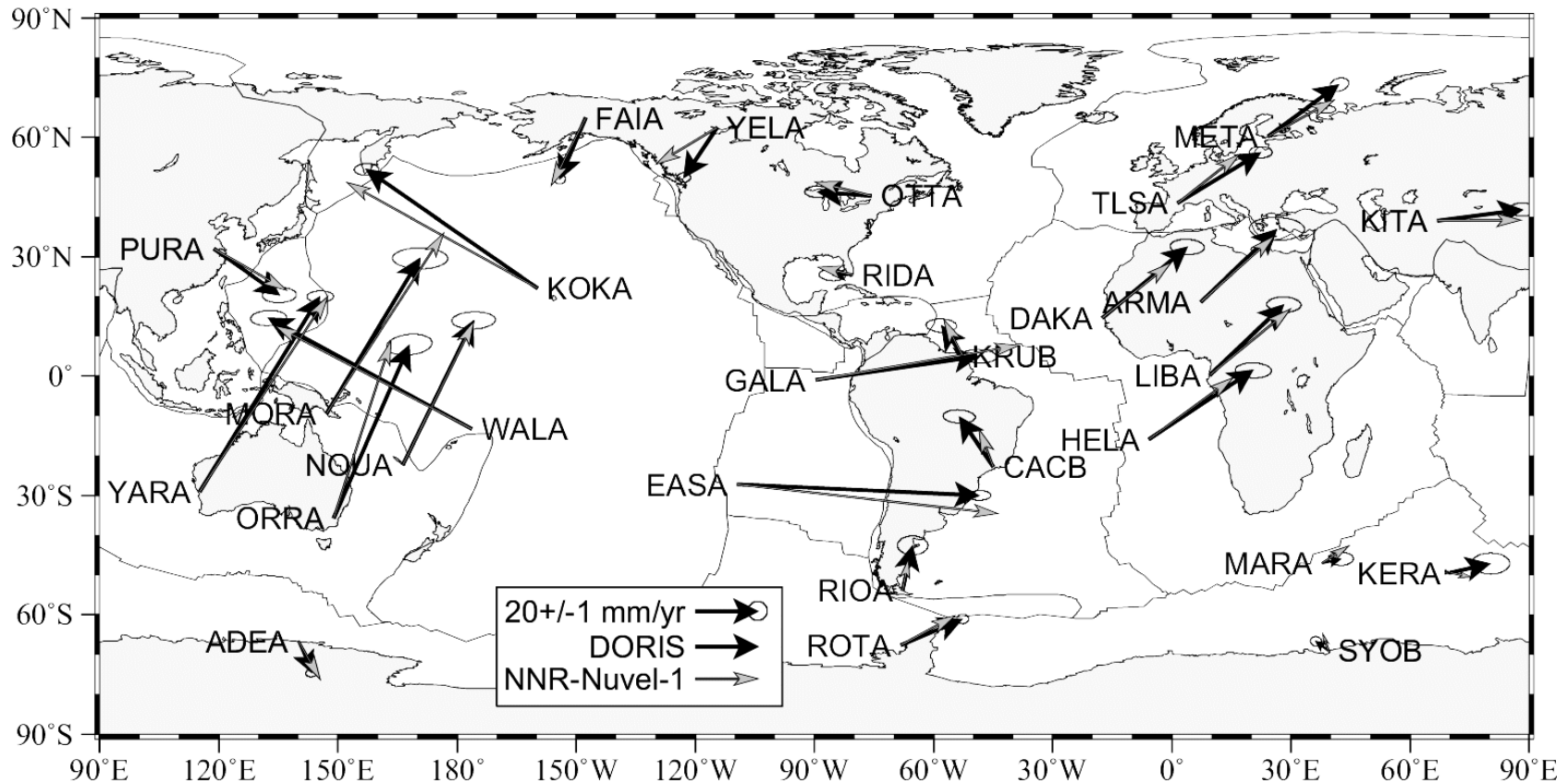


Previous results: DORIS/NUVEL1



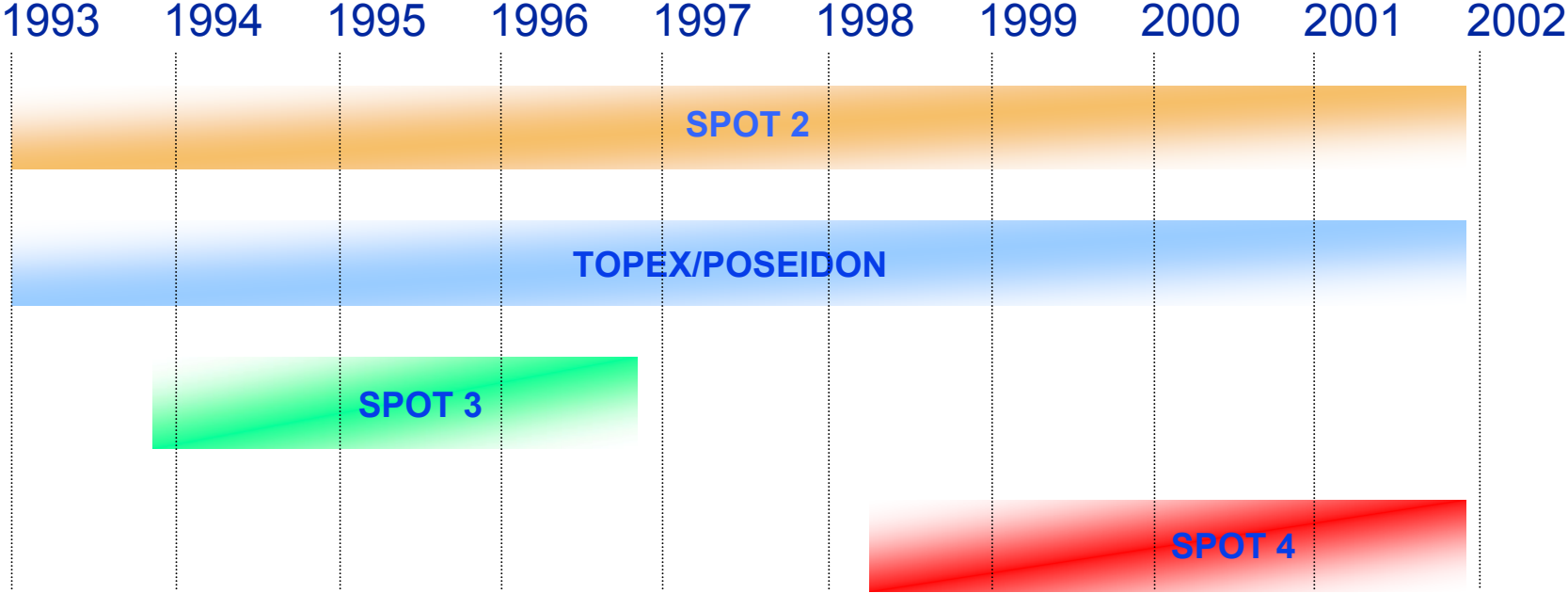
Créaux et al., 1998

Previous results: DORIS absolute velocities and NUVEL1-NNR



Créaux et al., 1998

Analysed Data

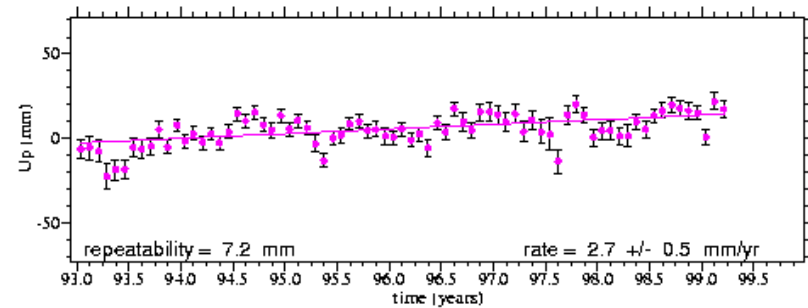
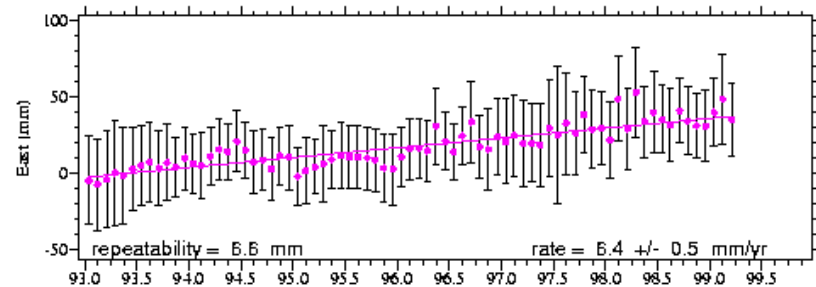
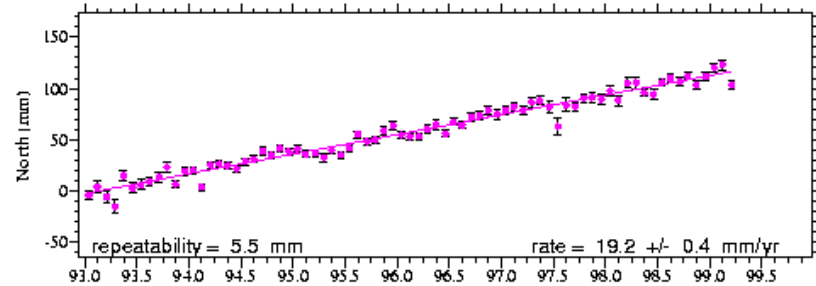


Coordinate time series

Ny-Ålesund - Doris Station

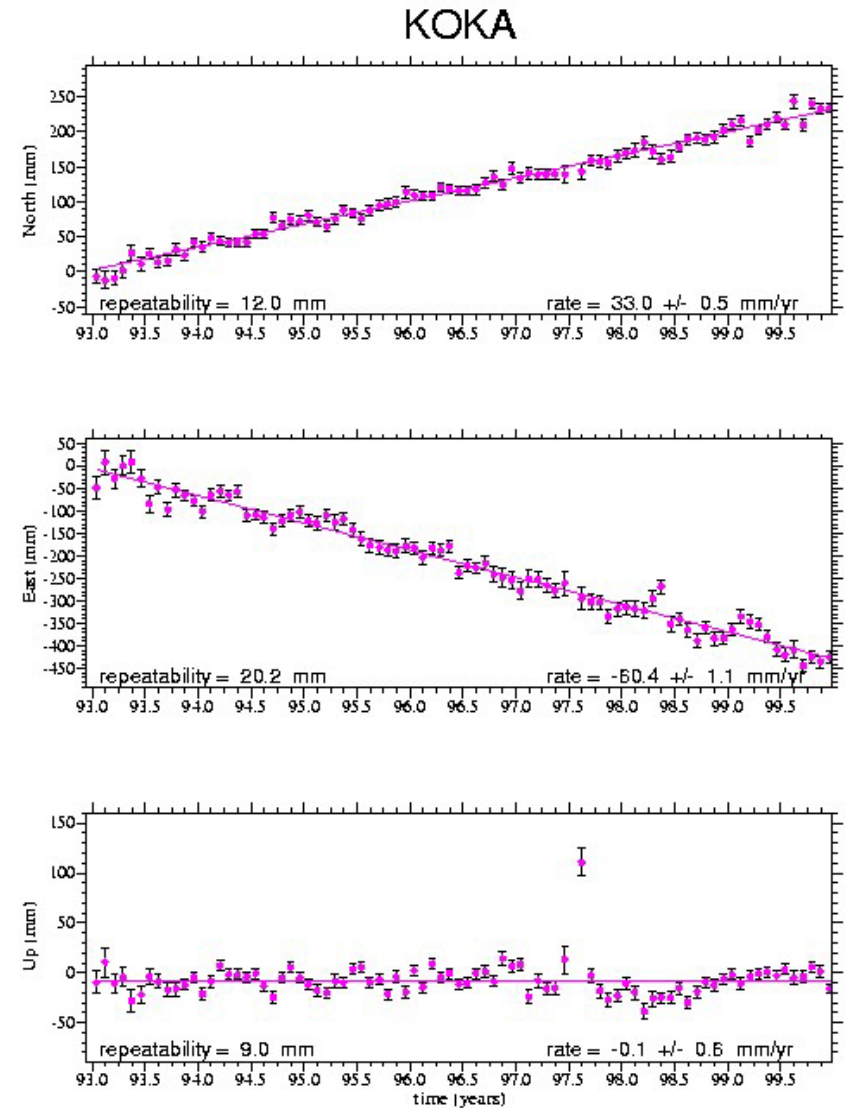


SPIA

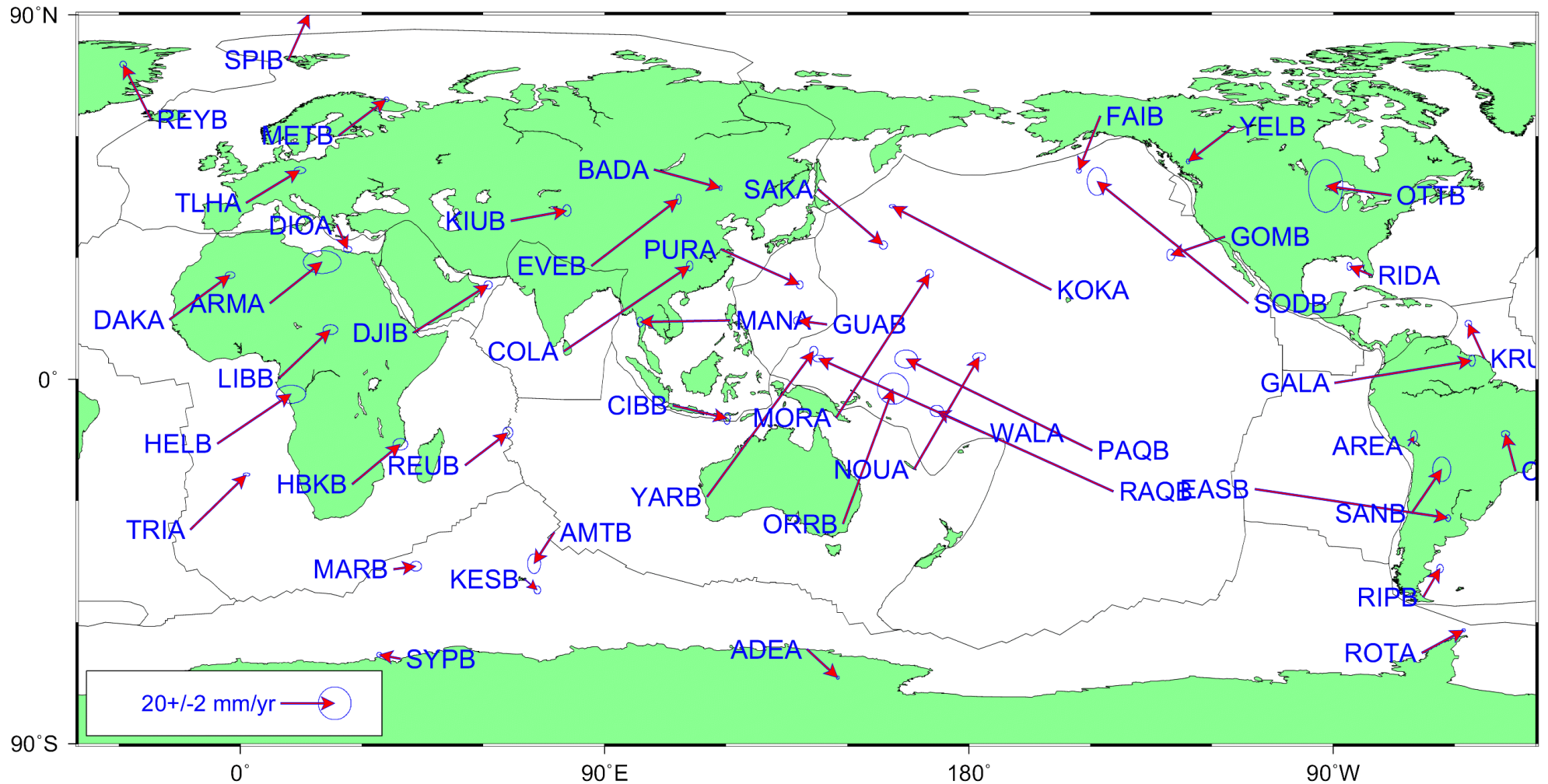


Coordinate time series

Koike Park (Kauai) - Doris Station



DORIS absolute velocities



Rotation vectors

Plate motions can be expressed through Euler poles and angular velocities.

Velocity of a station on a plate: $\mathbf{v} = \mathbf{\Omega} \times \mathbf{r}$

$\mathbf{\Omega}$: rotation vector of the plate

\mathbf{r} , \mathbf{v} : position and velocity vectors of the station

Observations equations:

$$V_{\varphi} = R(\omega_x \sin \lambda - \omega_y \cos \lambda)$$

$$V_{\lambda} = R(-\omega_x \cos \lambda \sin \varphi - \omega_y \sin \varphi + \omega_z \cos \varphi)$$

ω_x , ω_y , ω_z : plate angular velocity coordinates

φ_p , λ_p : plate pole coordinates

Ω_p angular velocity magnitude

Unknowns: $\Omega_p = \sqrt{\omega_x^2 + \omega_y^2 + \omega_z^2}$

$$\varphi_p = \sin^{-1} \frac{\omega_z}{\Omega_p}$$

$$\lambda_p = \tan^{-1} \frac{\omega_y}{\omega_x}$$

R : Earth's mean radius

φ , λ : station latitude and longitude

V_{φ} , V_{λ} : station north and east velocity

At least two beacons needed per plate sufficiently far away from active deformation zones

GEODVEL

GEODVEL : GEODesy VELOCITY model [Argus et al.]

➤ model of the angular velocities among 9 major plates, using observations from GPS, VLBI, and SLR

GLB1122 [VLBI, from C. Ma, Goddard Space Flight Center] data from 1979 to June 1999

CSR00I01 [SLR, from R. Eanes, Center for Space Research] data from 1976 to March 2000

GPS [from M. Heflin, Jet Propulsion Laboratory] data from 1991 to April 2001.

➤ sites assigned to plates on the basis of geological observations

Vector differences between the DORIS and GEODVEL velocities

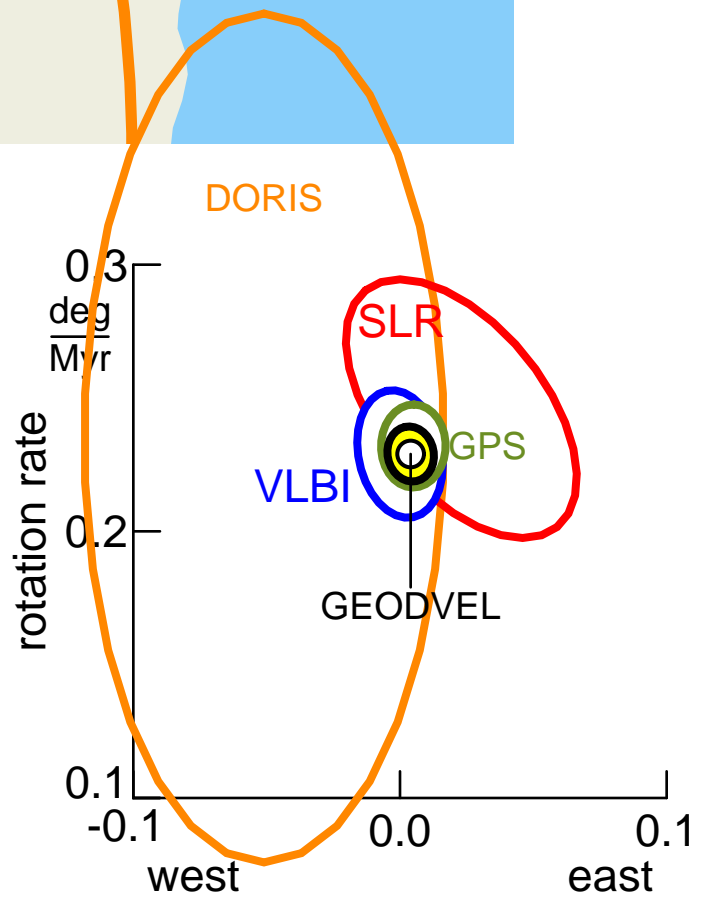
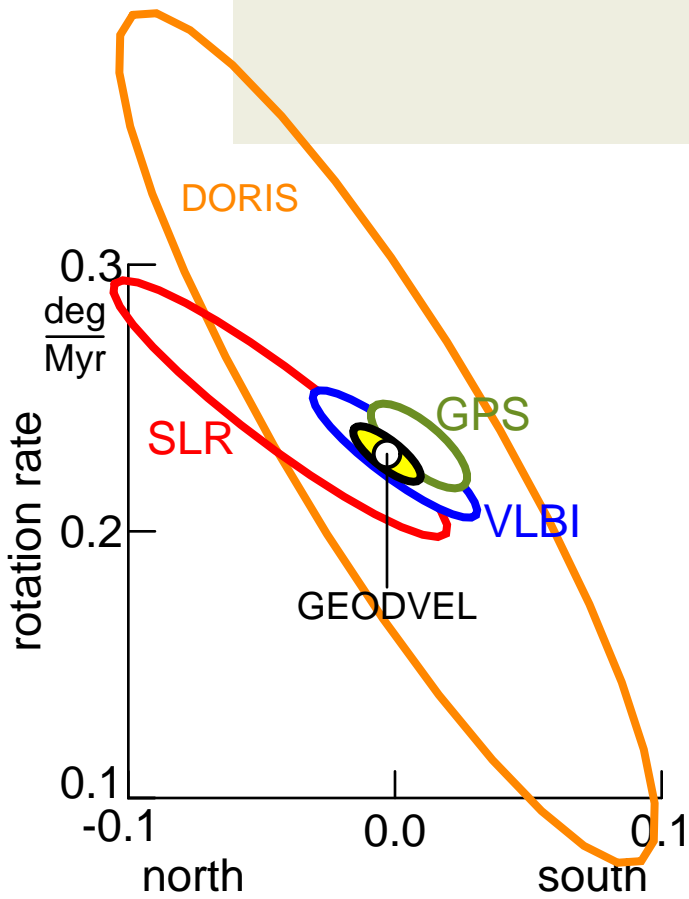
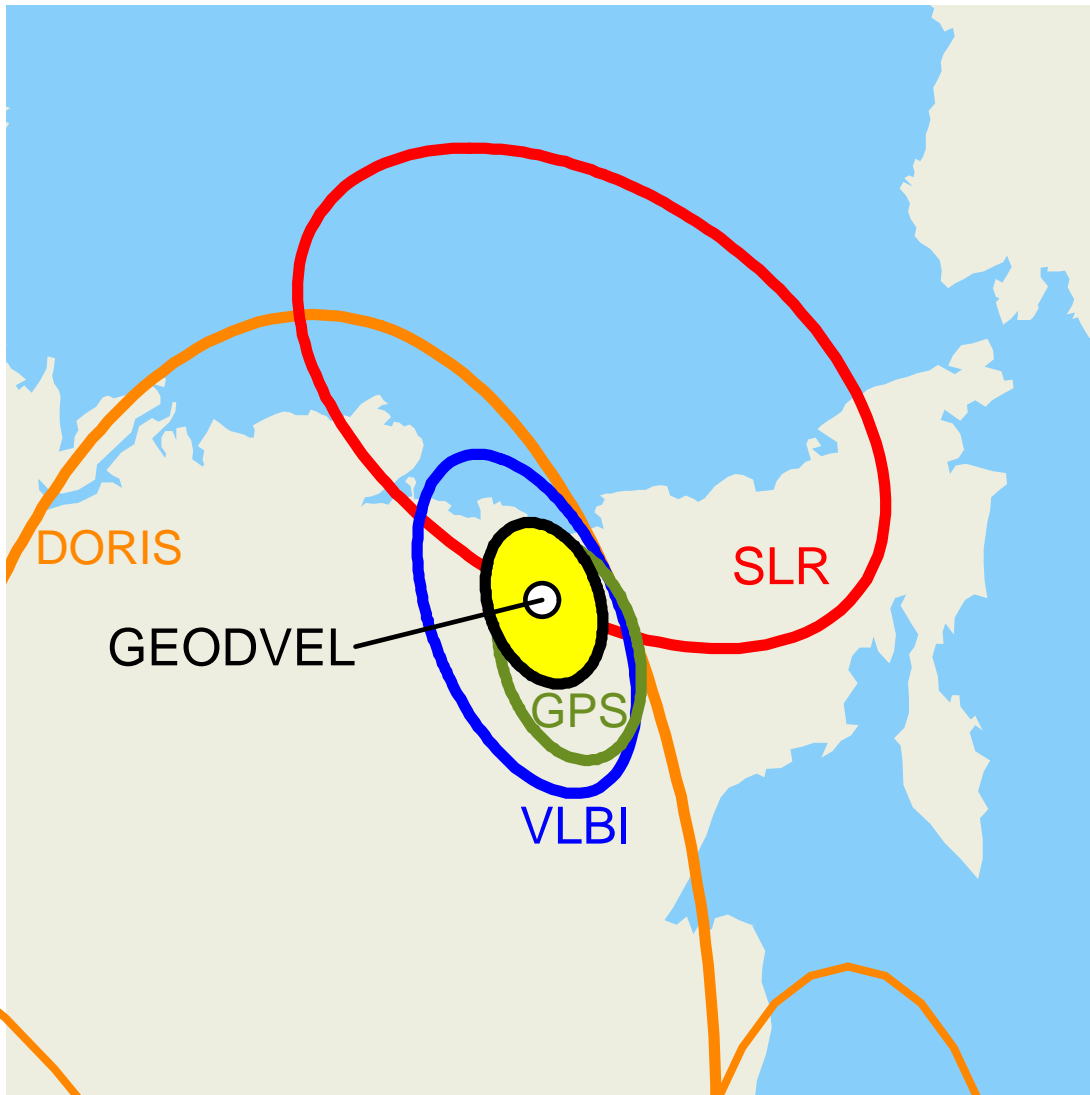
	Vector difference (deg/Myr)	Chi-square
EURA-NOAM	0.0548	3.9
NOAM-PCFC	0.0425	0.9
PCFC-ANTA	0.0643	15.7

Eurasia plate: TLSA, SPIA, META

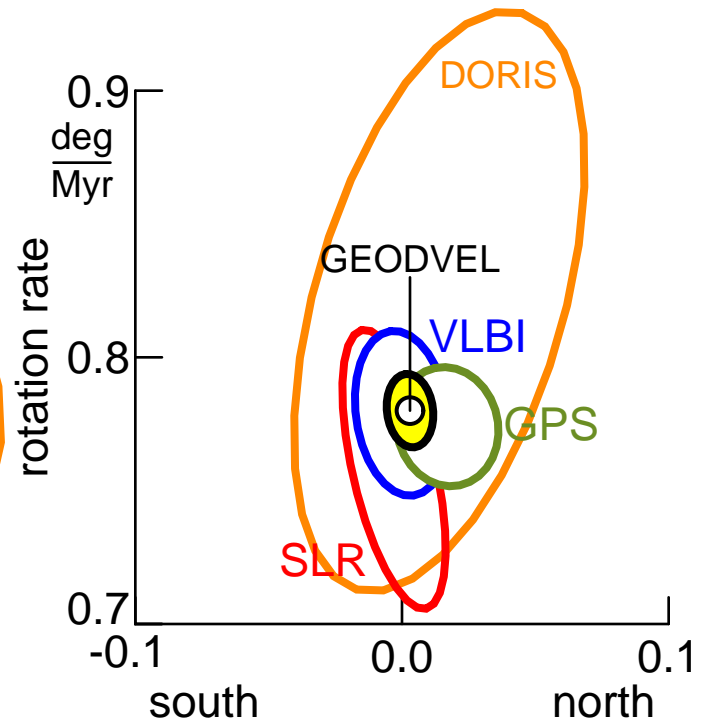
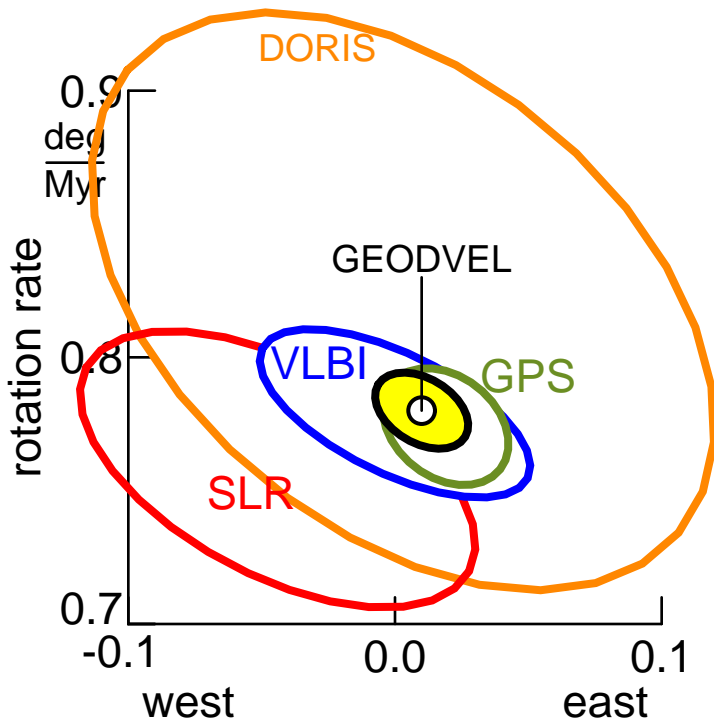
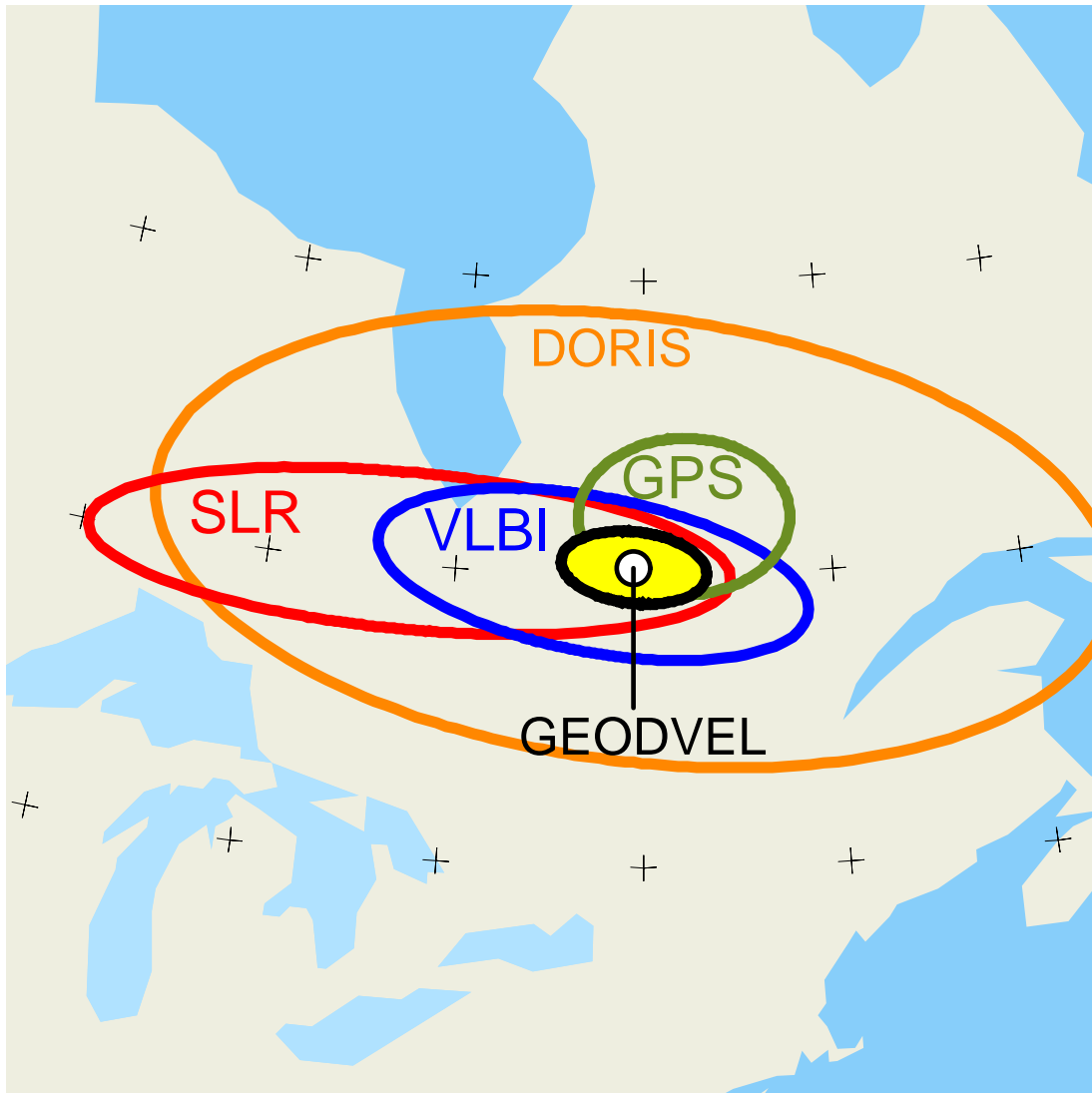
North America plate: YELA, RIDA, OTTA

Pacific plate: WALA, KOKA, PAQB, RAQB

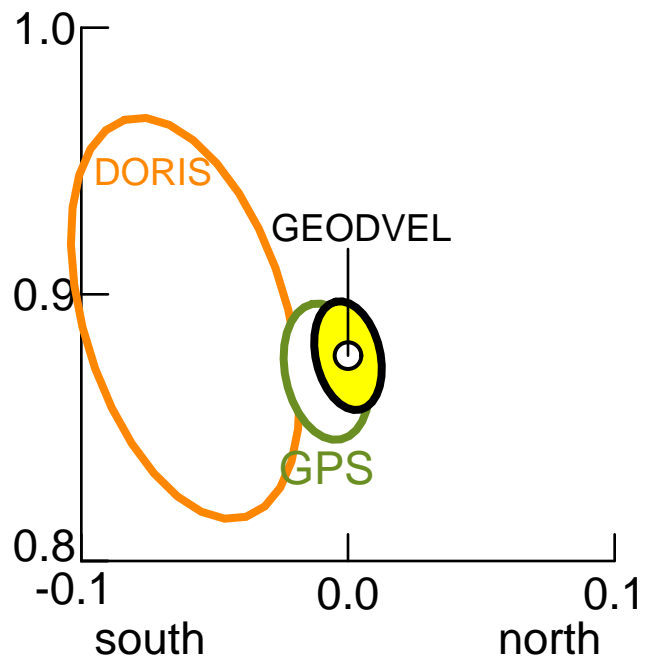
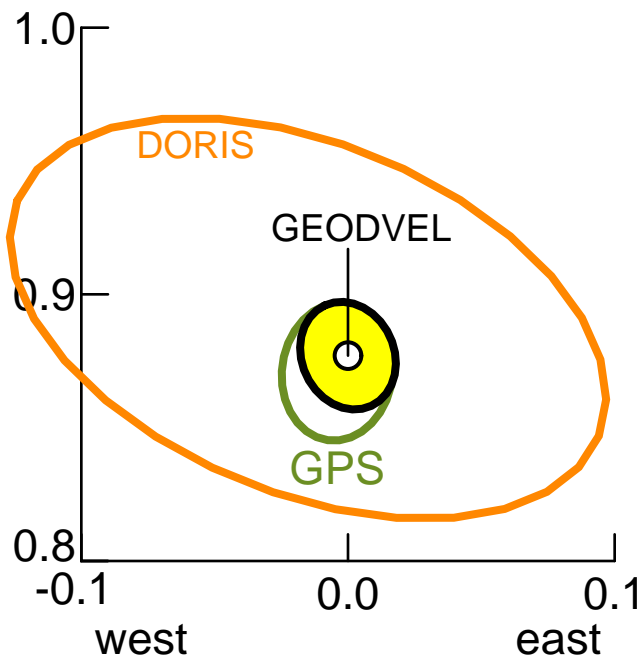
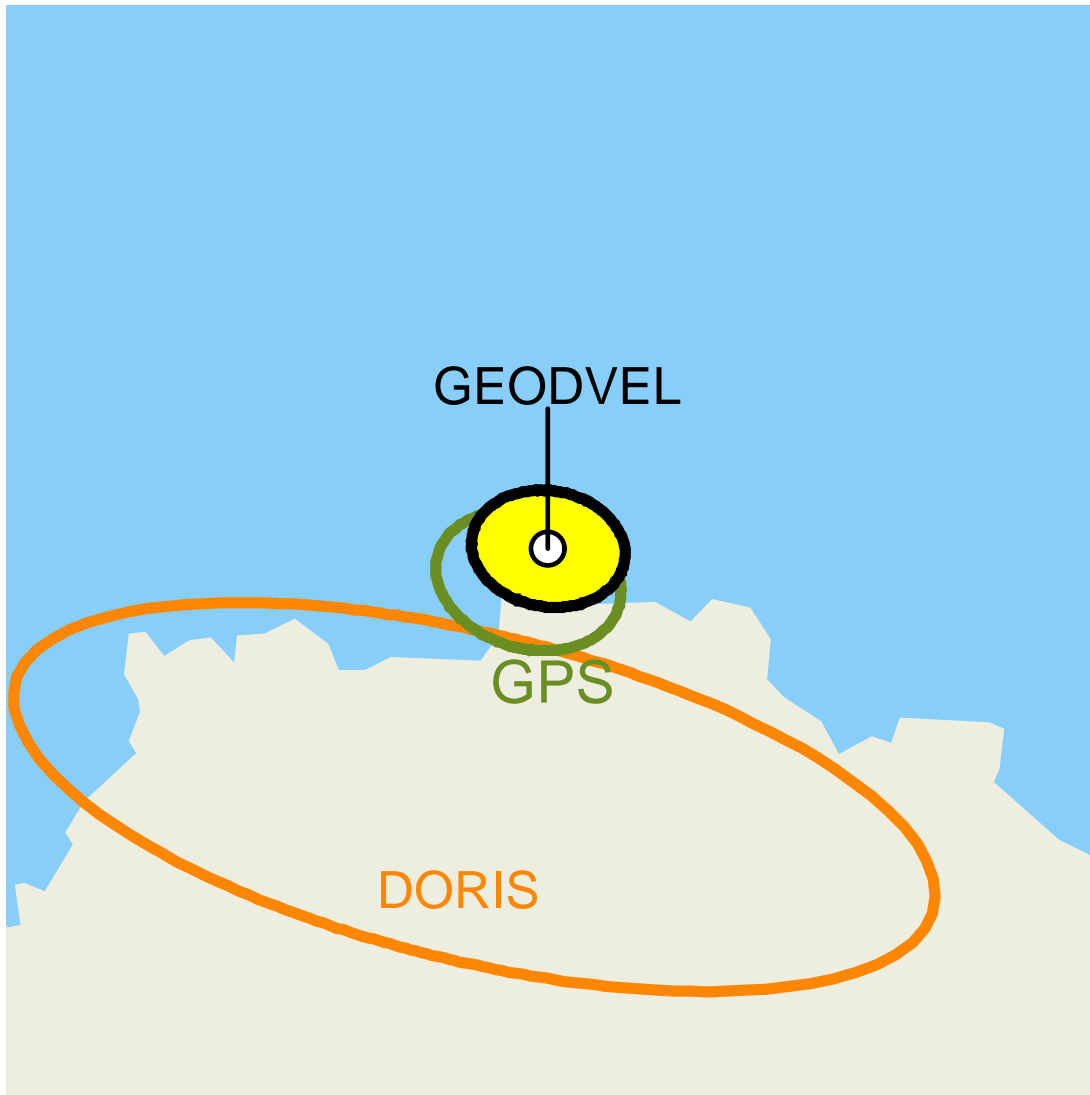
Eurasia–North America



North America–Pacific



Pacific–Antarctica



Several groups are using DORIS results for combination with other techniques

- Argus (JPL): including DORIS in GEODVEL (in process)
- Altamimi (IGN): plate model from ITRF2000 (in press)
- Gerasimenko (Institut of Applied Mathematics, Vladivostok, Russia): definition of Kinematics Reference Frame (paper in preparation), combination with other techniques

DORIS bring key new constraints to crustal movements for plates few or not covered by other techniques (ANTA, NUBIA, SOMALIA)

Suggestions for new DORIS installations

- Caribbean and Cocos plates
- Indian plate (second site)
- Greenland (cover of NOAM; ice studies)