



# Early results on the validation of the horizontal velocities from the cumulative solution based IDS 09

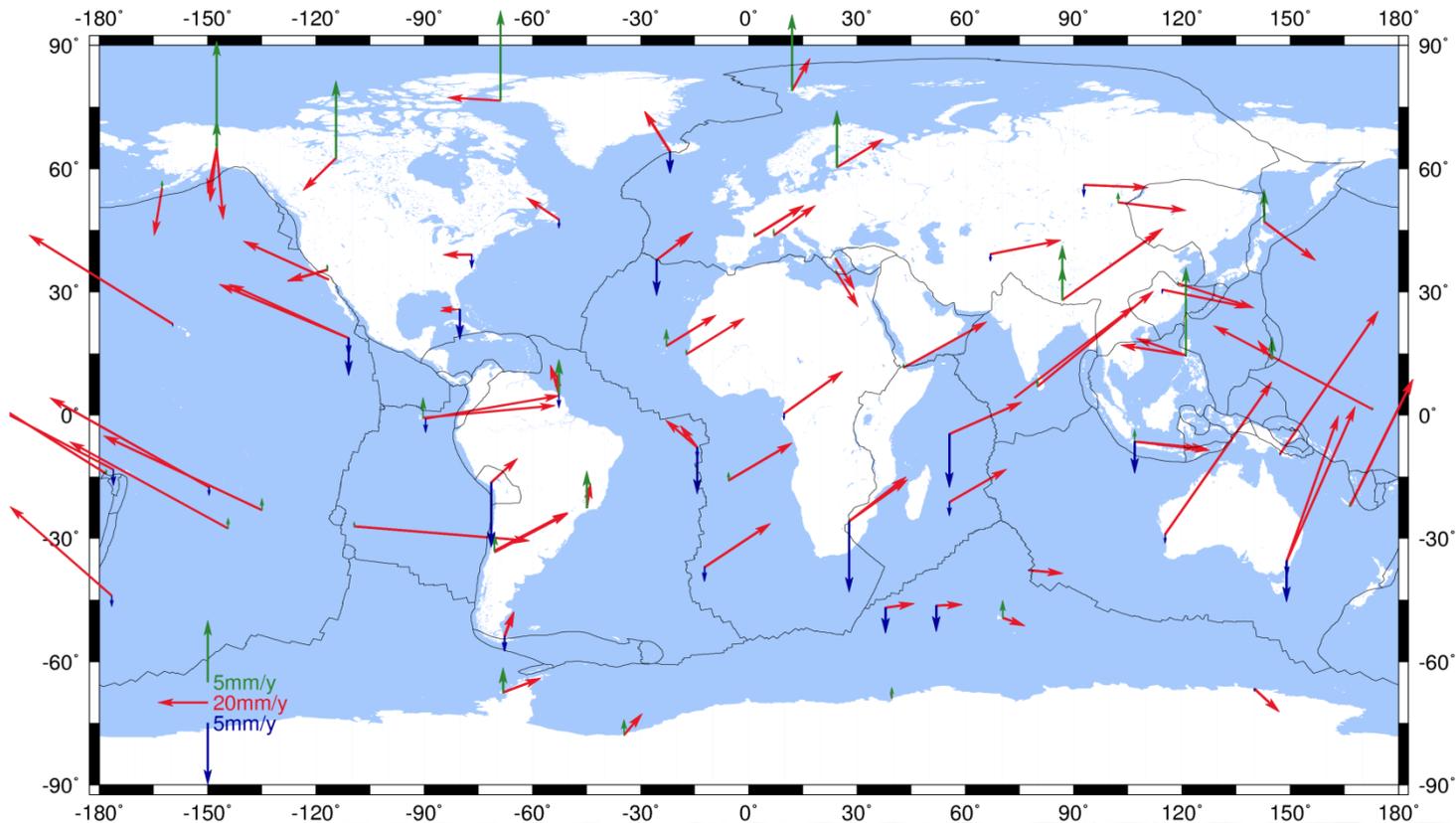
Guilhem Moreaux

- **Construction of a cumulative position and velocity solution is part of the internal validation process of the IDS contribution to ITRF2014.**
  - **In addition and in response to P. Willis during last AWG in Toulouse, the IDS agreed to take over from Pascal the DPOD activities.**
- **IDS CC has and will have to compute cumulative solutions**
- **As it is a new task for the IDS CC, the very first solution must be validated by comparison to external models.**



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## Horizontal Velocities from IDS-TRF2014

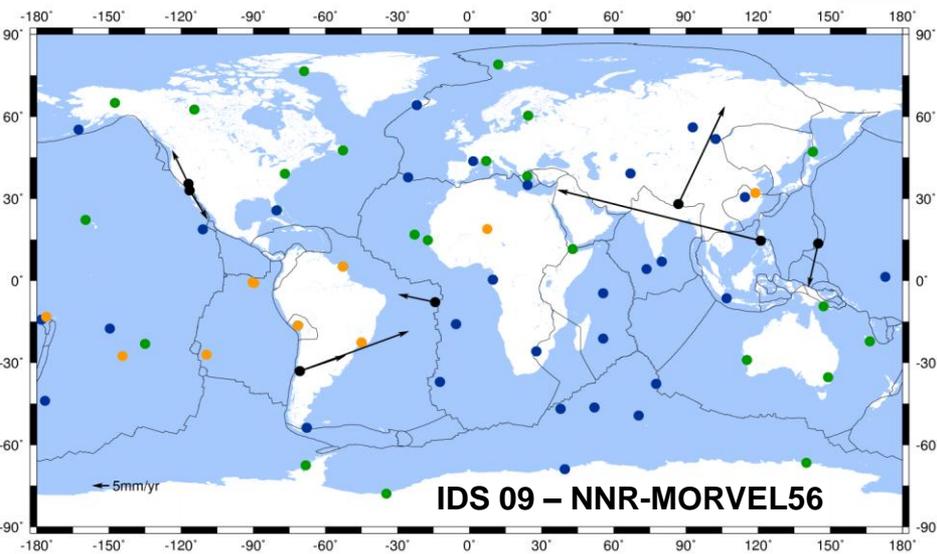
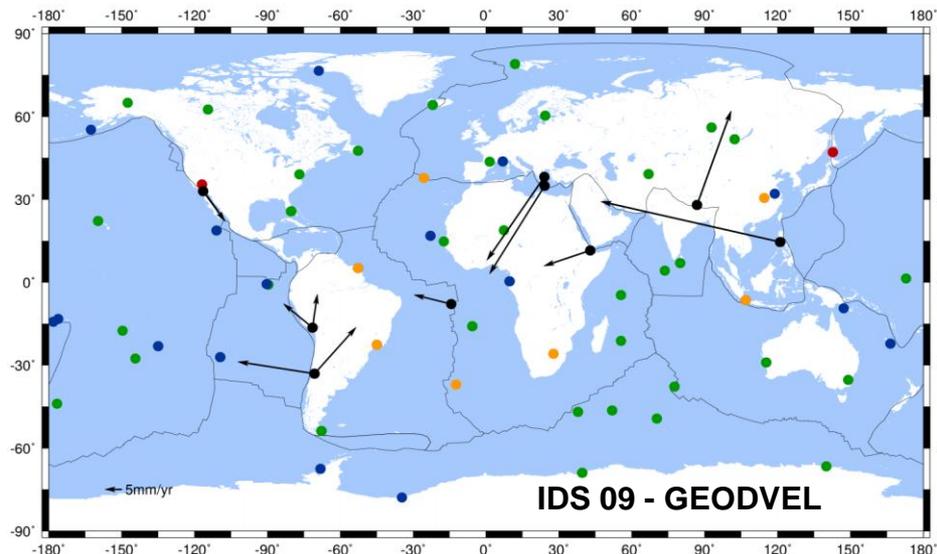


- ❑ **IDS 09** (resp. **IDS 03**) includes **57** (resp. **53**) discontinuities in position
  - ✓ **Concern 30** (resp. **28**) over 71 DORIS sites.
  - ✓ **25** (resp. **14**) with seismic origin.
  - ✓ **8** (resp. **06**) with beacon or antenna origin (ex: USO change).
  - ✓ **24** (resp. **33**) with unknown origin.



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# Comparison of Horizontal Velocities IDS 09 vs GEODVEL & NNR-MORVEL56



Green: 0.0-2.5mm/yr – Blue : 2.5-5.0mm/yr – Orange: 5.0-7.5mm/yr – Red: 7.5-10mm/yr – Black > 10mm/yr

## GEODVEL (GEODesy VELOCITY – Argus et al. 2010)

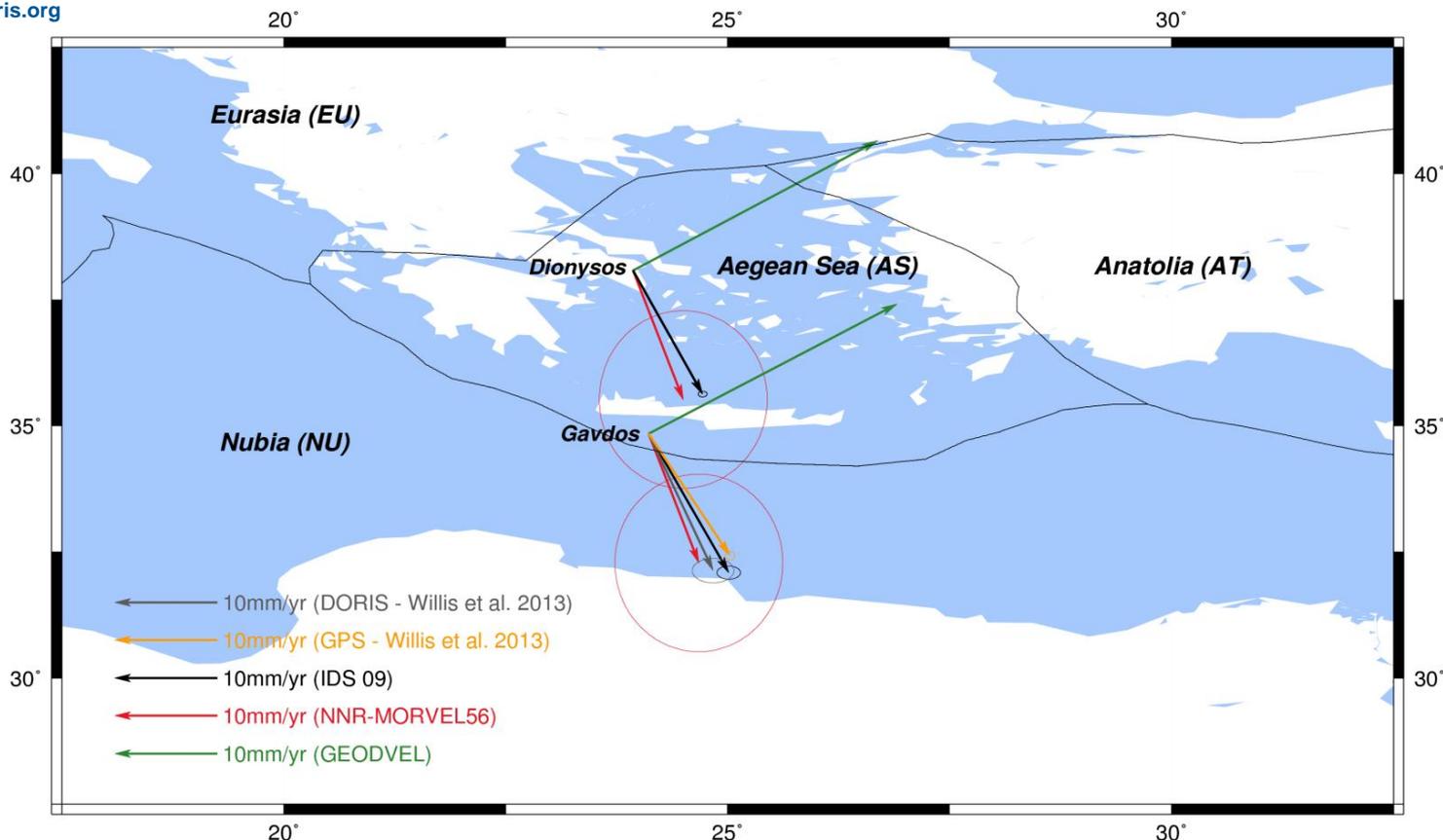
- 11 plates.
- Data: DORIS, GNSS, SLR, VLBI.
- Data Time Span: 1976 -2007.
- DORIS contribution from IGN AC.
- RMS of differences:
  - North: 6.2 mm/yr
  - East: 10.3 mm/yr

## NNR-MORVEL56 (Argus et al. 2011)

- 56 plates.
- Extension of the MORVEL model (25 plates).
- Geologic data.
- Data Time Span: -3 200 000 / -780 000 yr.
- RMS of differences:
  - North: 5.4 mm/yr
  - East: 11/1 mm/yr

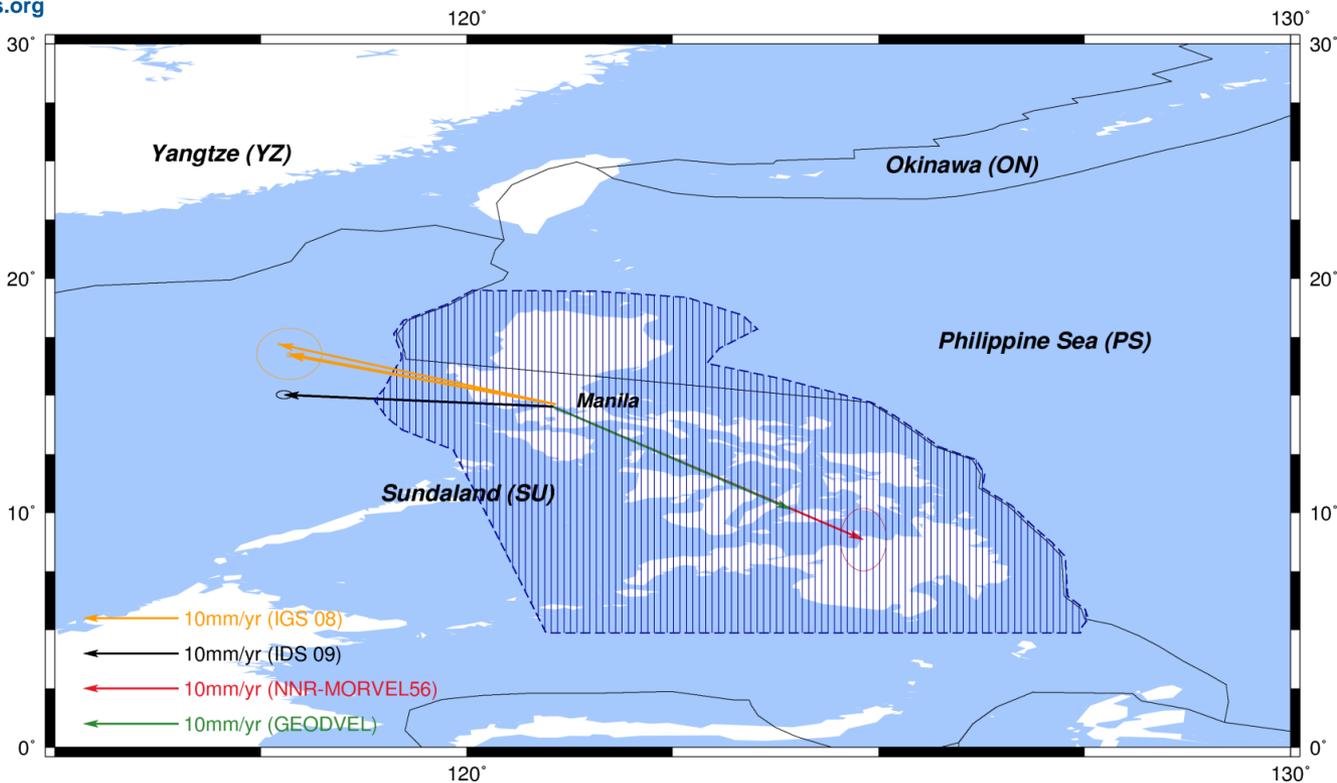
Highest differences occur in plate boundaries or in seismic active zones. Nevertheless...

## Horizontal Velocities – Dionysos and Gavdos



- DORIS estimations are coherent with NNR-MORVEL56 and Willis et al. (2013) ones.
- DORIS also shows a SW motion of the Aegean Sea relatively to Eurasia at a speed of 30mm/yr.
- GEODVEL default is due to no Aegean Sea plate in the model so for that model the motions of Dionysos and Gavdos are modeled by the Eurasia parameters.

## Horizontal Velocities - Manila



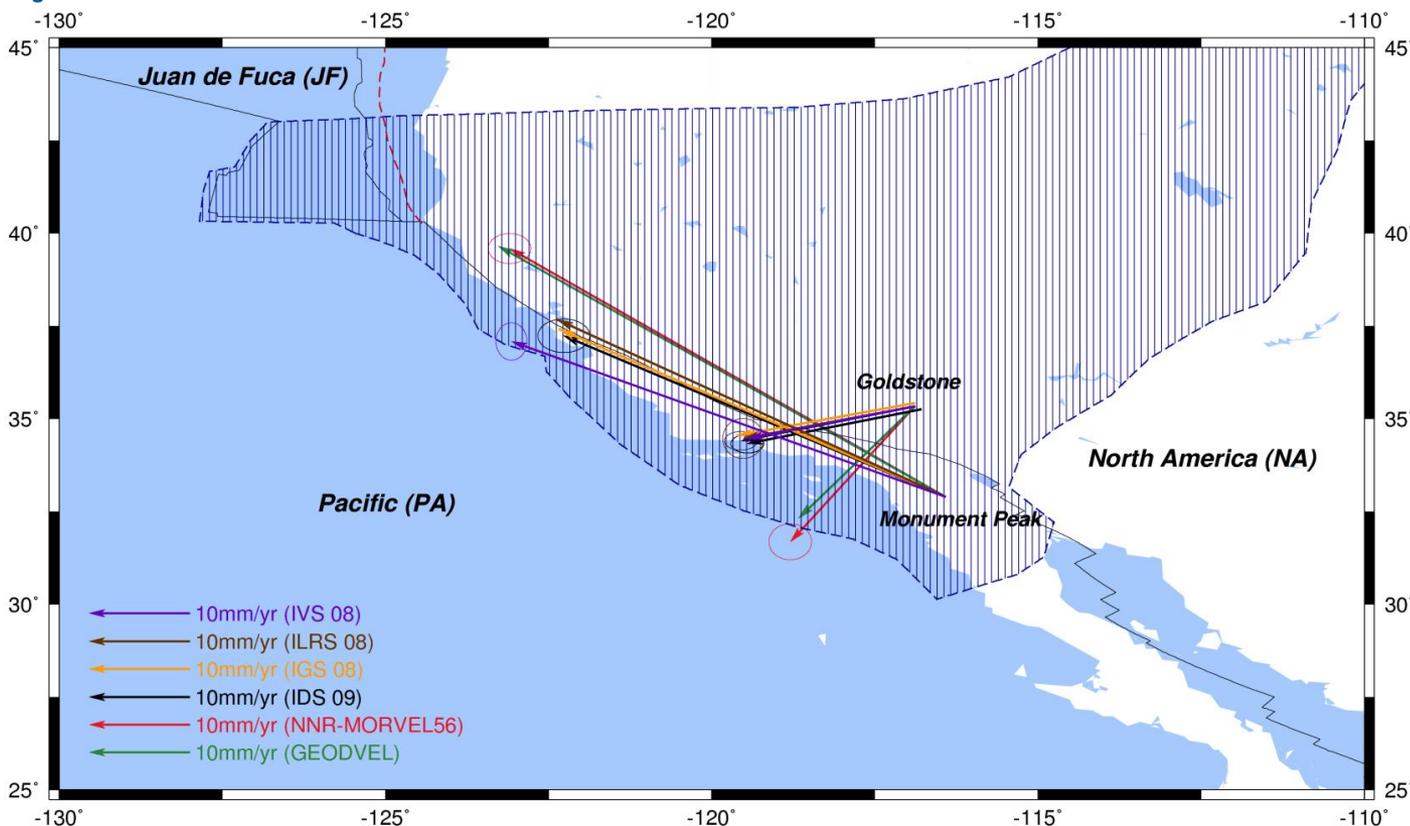
- ❑ DORIS velocity differ very much (in direction mainly) from both GEODVEL and NNR-MORVEL56 estimations.
- ❑ DORIS estimate is similar to the GPS PIMO site (10km NE from MANA-MANB) as extracted from IGS 08.
- ❑ Bird (2003) → Manila belongs to the Philippines orogen zone.  
→ Orogen must explain MORVEL and NNR-MORVEL56 defaults.
- ❑ DORIS velocity is also compatible with GPS LAOA estimations from Rangin et al. (1999)  
→ counter-clock rotation of Luzon block / Sundaland.



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## Horizontal Velocities – Goldstone & Monument Peak

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- ❑ Goldstone and Monument Peak are located to the east and to the west of the Pacific-N. America plate boundary (the San Andreas Fault).
- ❑ DORIS velocities are similar to GNSS, Laser and VLBI estimations as extracted from ITRF2008.
- ❑ DORIS estimations differ from the plate models in direction for Goldstone and amplitude for Monument Peak.
- ❑ Next: comparison to dense GPS network estimations.

- **IDS 09 horizontal velocities show good agreement (differences smaller than 5mm/yr) with the two models for most of the beacons.**
- **Larger differences occur at plate boundaries or in active seismic areas.**
- **Some differences can be explained and external comparison show that IDS 09 estimations are realistic.**



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## What's next ?

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- **Rotation parameters of some plates will be estimated when possible.**
- **IDS 09 vertical velocities will be compared to GIA models and to GNSS ULR6 (La Rochelle University) estimations at coastal sites. Sites like Thule will be of special concern.**
- **That study is planned to be published as a paper with Frank, Laurent, Pascal, Donald Argus, Alvaro Santamaría-Gómez and Médéric Gravelle as co-authors.**
- **The results will also be presented during next AGU as poster #64285 on December 15th in section G23B.**
- **IDS 09 velocities will be compared to ITRF2014 solutions from DGFI, IGN and JPL.**
- **IDS 09 cumulative solution will serve as reference for the future DPOD solutions.**