

ASSESSMENT OF SELF-SHADOWING EFFECT ON SWOT

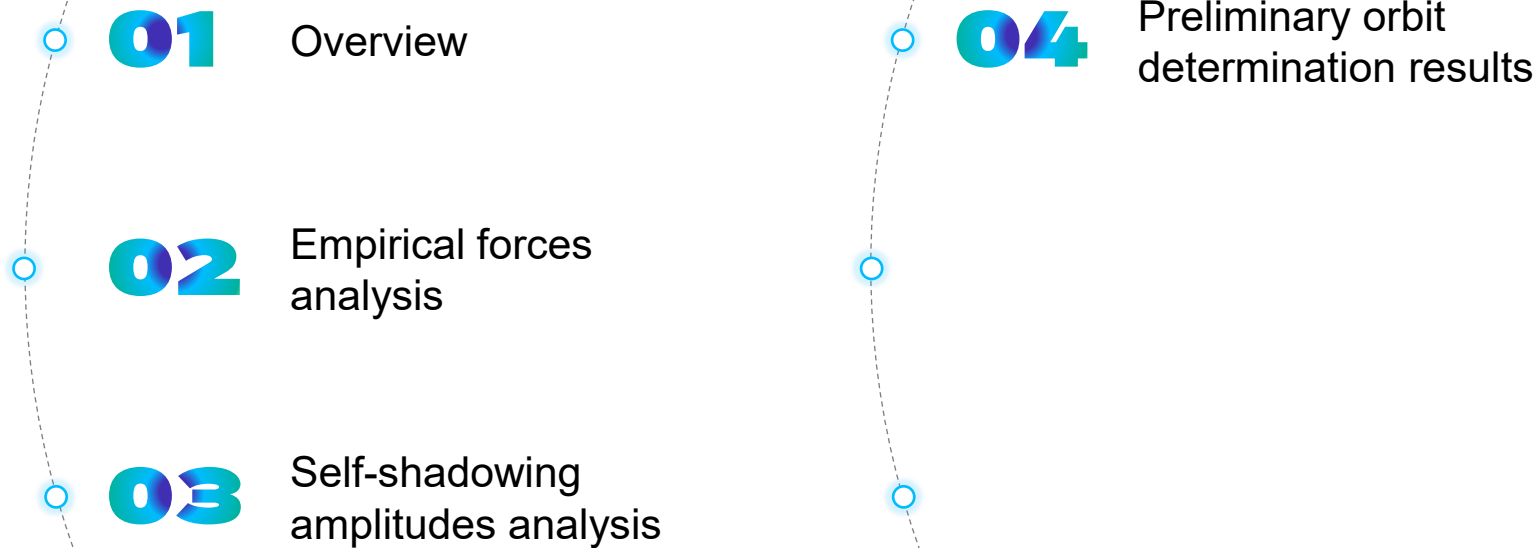
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SUMMARY

- 
- 01** Overview
 - 02** Empirical forces analysis
 - 03** Self-shadowing amplitudes analysis
 - 04** Preliminary orbit determination results

CONTEXT

1. OVERVIEW

Scientific requirements for future missions:

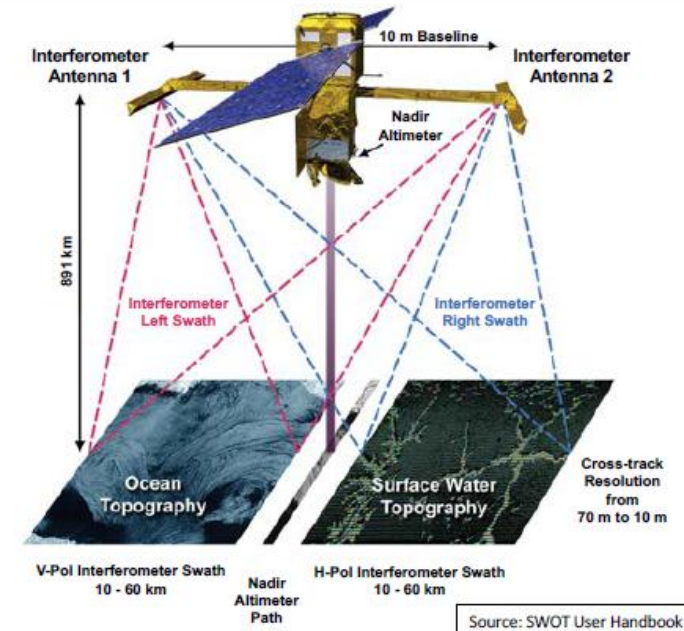
reduce the regional orbit error budget for Mean Sea Level estimation to 1 mm per decade

- Need to look into all contributors to the orbit error
- Analyze the impact of self-shadowing modelling on the orbit error budget

SWOT mission:

- launched on December 16, 2022 providing global survey of oceans and inland water surface elevations.
- Three tracking systems: GPS, DORIS, SLR
- Precise orbit determination (POD) critical to achieving SWOT's science objectives.
- 15 mm (RMS) radial orbit accuracy requirement.

Surface Water and Ocean Topography (SWOT) Mission
Launched December 16, 2022: ~900 km Altitude

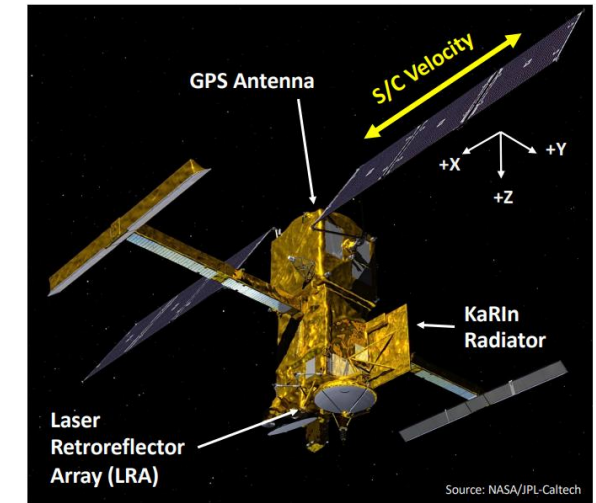


SWOT SATELLITE

1. OVERVIEW

Relevant elements on SWOT architecture

- S/C velocity along +/- Body X directions.
- -Y is always toward the Sun.
- Spacecraft performs yaw flips (apx. every 78 days) to keep radiator (i.e., +Y) in shade.
- One solar panel on each side of spacecraft bus along body-fixed +/- X directions.
- Radiators are located on +Y side of the spacecraft.
- Solar panels are always oriented towards -Y, taking three β -dependent positions.
- For CNES POD, the Solar Radiation Pressure (SRP) model is a cube with two solar panels



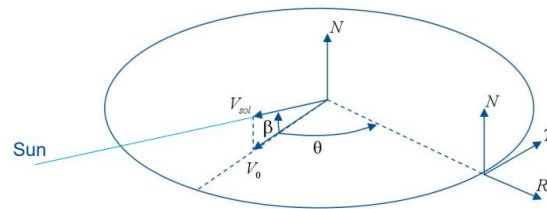
β	Solar array angle
$[0^\circ - 6^\circ]$	0°
$[6^\circ - 25^\circ]$	12°
$> 25^\circ$	30°

EMPIRICAL FORCES ANALYSIS

2. EMPIRICAL FORCES ANALYSIS

Orbit Determination using ZOOM Software, with POE-G standard for multiple beta-cycle

Analysis of once-per-revolution empirical accelerations along-track (T) and cross-track (N) computed with the reference at the subsolar point.



θ : angle between the current satellite orbital position and the subsolar point

β : angle between the orbit plane and the sun direction

Empiricals (1/rev) are written as:

$$T = T_{co} \cdot \cos(\theta) + T_{si} \cdot \sin(\theta)$$

$$N = N_{co} \cdot \cos(\theta) + N_{si} \cdot \sin(\theta)$$

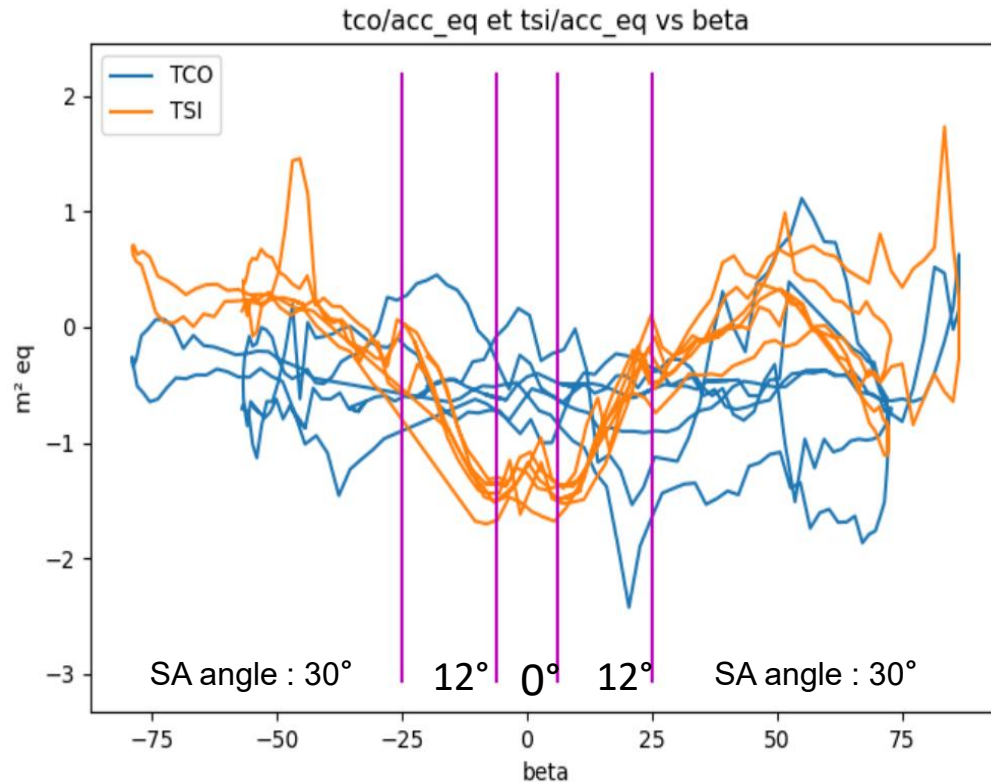
1/rev are divided by the acceleration on the satellite produced by a black square of 1m^2 in normal lighting.

-> better acknowledge the 1/rev amplitude wrt satellites surfaces

$$acc_{eq} = \frac{\Phi * s}{c * m} = 2.28\text{e-}9 \text{ m/s}^2$$

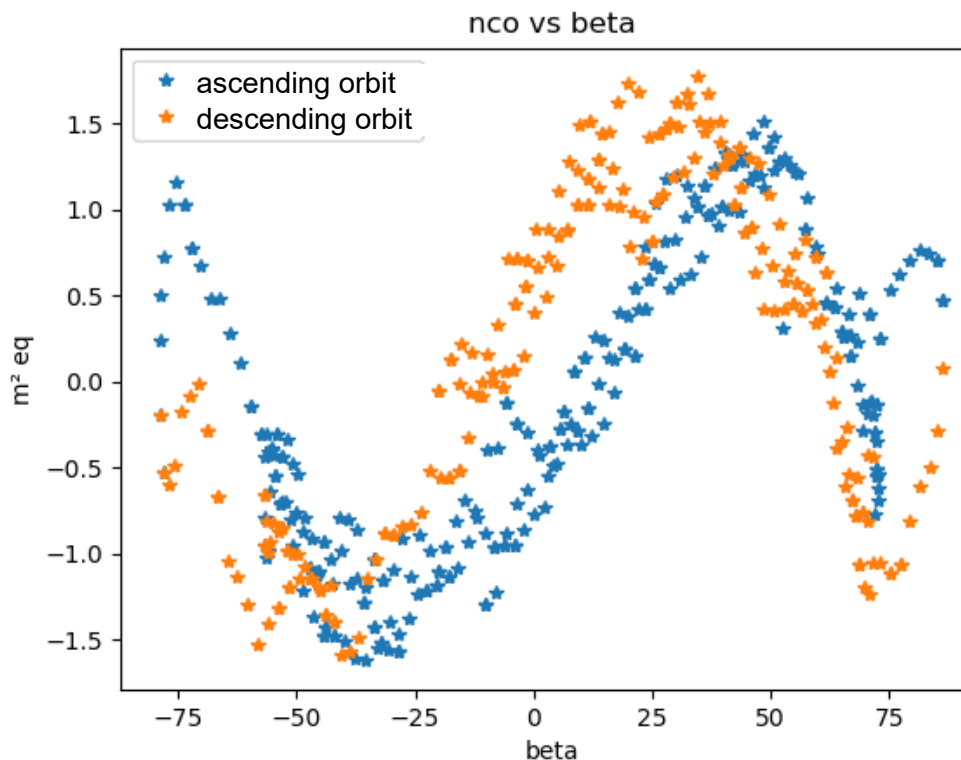
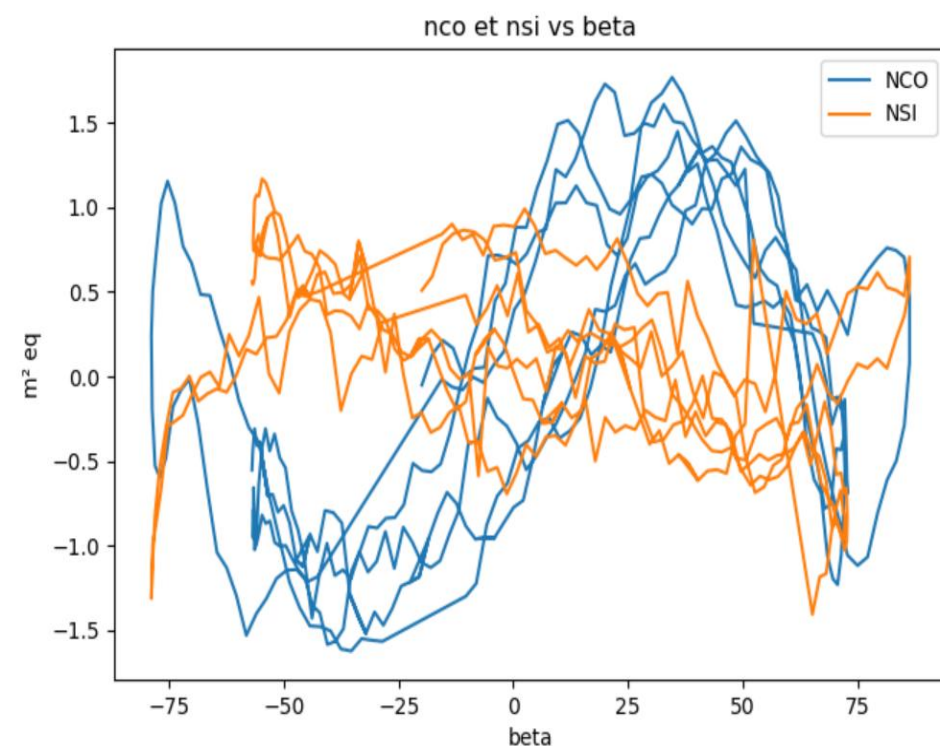
With Φ , solar flux, s , square surface, c , light velocity, m , satellite mass

BETA-DEPENDANT SIGNATURE - TANGENTIAL



- Tco signal absorbs mostly drag modelling errors. It is mostly correlated with the solar activity and not with the beta angle.
- Tsi signal absorbs mostly SRP modelling errors. A correlation both with the beta angle and with the solar array angle is visible.
- $\beta > 25^\circ$: 1/rev flat and close to $0m^2$ error.
- $\beta < 25^\circ$: 1/rev peaks up to $1.5m^2$.

BETA-DEPENDANT SIGNATURE - NORMAL



- Nsi signal is flat w.r.t. β , no relevant dependencies are observed.
- Nco signal shows a sinusoidal dependency w.r.t. β , up to 1.5m^2 .
- There is a dependency between ascending or descending orbits when viewed from the sun direction. It could be correlated to the heat flow from the radiators on face $-Y$.

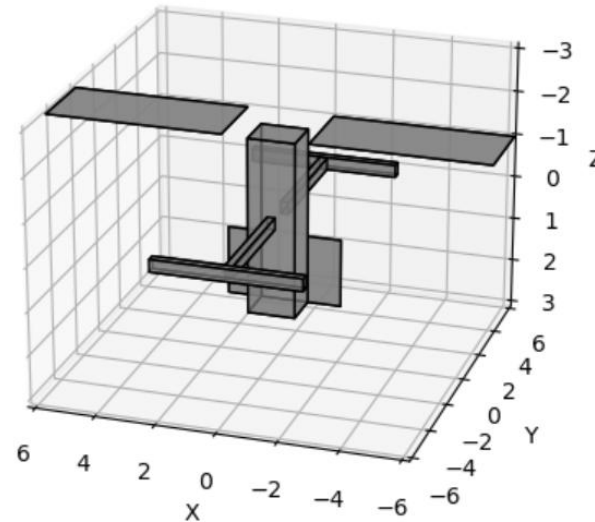
SRP WITH AND W/O SHADOW

3. SELF-SHADOWING AMPLITUDE ANALYSIS

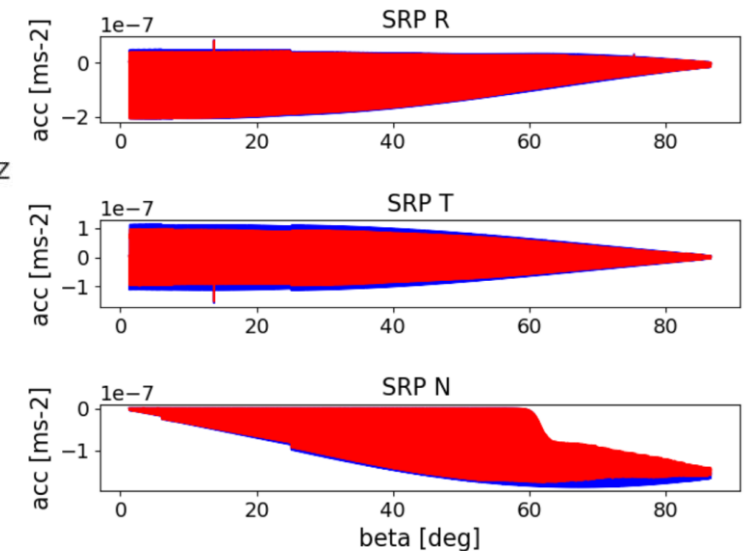
- Acceleration computation using GINS software
- Three models, one for each solar array position
- Satellite modelled with a main body, solar arrays, Karin and radiators

Main shading effects on:

- The tangential acceleration, for $\beta < \sim 40^\circ$
- The normal acceleration, for $\beta > \sim 60$, with a bias

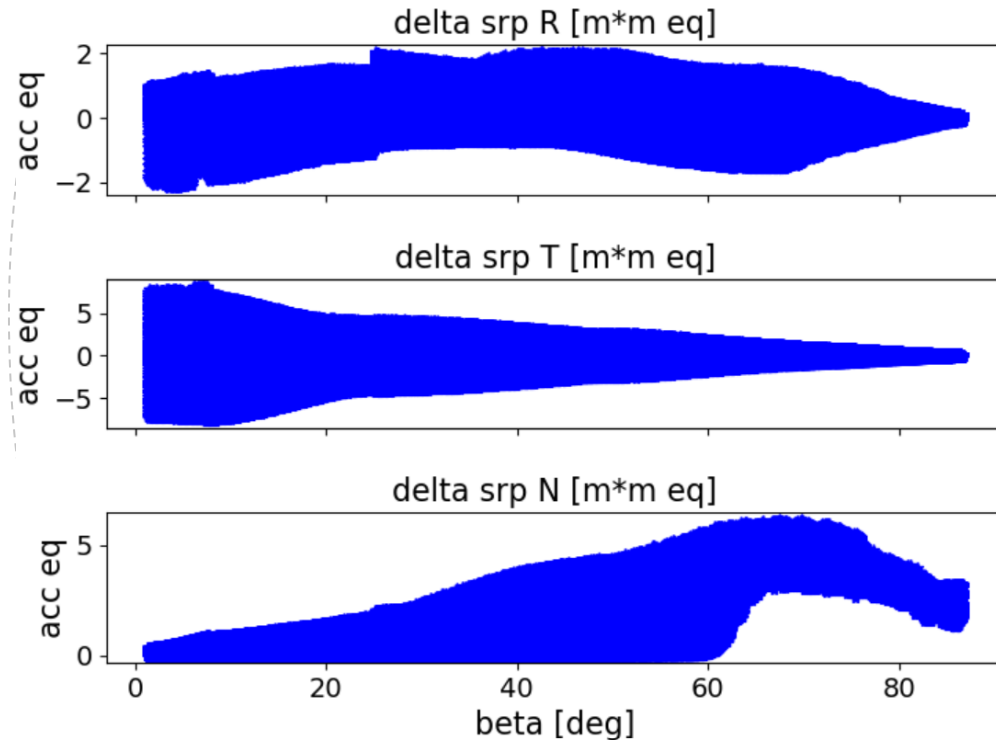


3D model for $\beta < 6^\circ$



SRP in RTN, blue without self shadow, red, with self shadow

SRP DIFFERENCE WITH AND W/O SHADOW



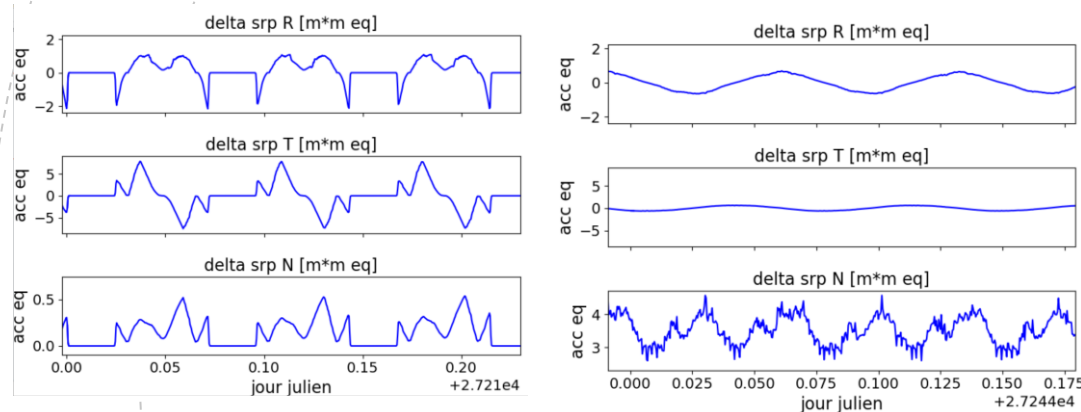
Tangential :

- Strongest effect occurs at low beta angles, with the shadow of the panels on the $\pm X$ faces (5.4 m^2).
- Shadows from the central body and the KaRIn reflector on the $\pm X$ faces of the KaRIn boom as beta increases (up to 2.3 m^2).
- From around beta $\sim 70^\circ$, the impact is less than 1 m^2 .

Normal:

- $< 1 \text{ m}^2$ for beta $< 20^\circ$.
- The central body casts a shadow on the radiators (up to 3.4 m^2).
- A bias appears at high beta angles: part of the $-Y$ surfaces are always in the shadow of another face.

ACCELERATION DIFFERENCE WITH AND W/O SHADOW



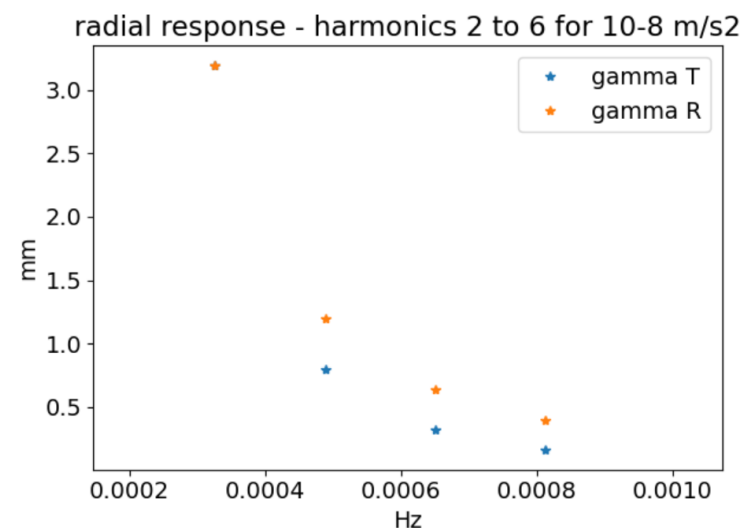
$\text{Beta} \cong 0 \text{ degré}$

$\text{Beta} \cong 75 \text{ degré}$

the signature of the acceleration difference is mainly at the orbital period, along with a bias in some cases.

The empirical terms at the orbital period will absorb the first-order harmonic errors caused by the lack of modeling of shadowing effects.

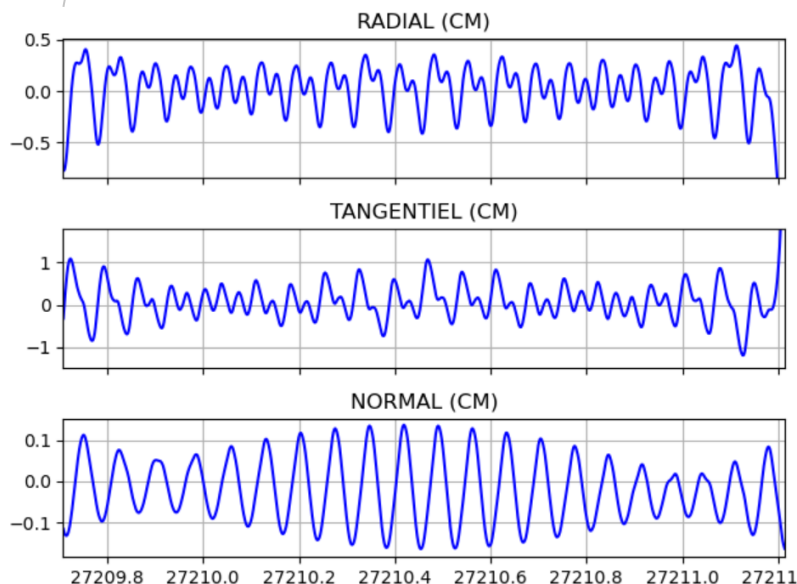
Higher order errors will not be compensated by the 1/rev and will participate in the orbit error.



For a maximum harmonic of 5 m^2 (in T, $\beta = 0$), we obtain an acceleration of approximately 10^{-8} m/s^2 , corresponding to a second-order harmonic with an amplitude of 3 mm.

ORBIT DIFFERENCE WITH AND W/O SHADOW - ZOOM

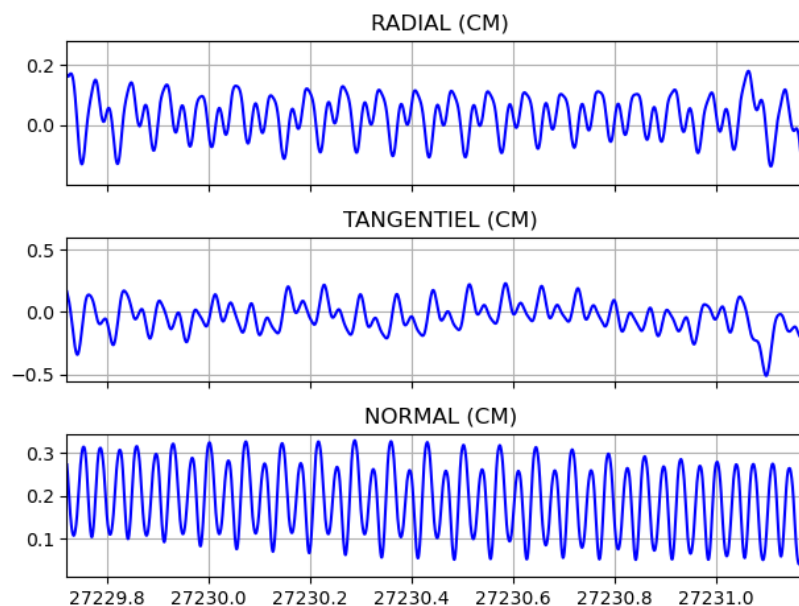
Preliminary work using ZOOM software and the acceleration from GINS instead of the ZOOM nominal SRP model.



β close to 0° :

1cm error on T, with signatures at 1/rev, 2/rev

0,1cm error on N, unbiased



β close to 60° :

0,2cm error on T, with signatures at 1/rev, 2/rev

0,1cm error on N, 0,2cm bias

CONCLUSION

Validation of the amplitude of the self-shadowing effect on the satellite SWOT

Preliminary testing in ZOOM

Futur work:

Re run SWOT orbits on a few beta cycles in ZOOM and analyse the results

Remarks:

This analysis doesn't take into account multiple reflexion, for instance the corner main body-radiators

The normal dependancy to ascending/descending orbits, remains to be investigated, starting by looking into thermal effects