

IDS WG Integrated Clock Correction Strategies for DORIS – Status and first results

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1.1 Co-Location of DORIS Clocks

Clock Co-Location in Space

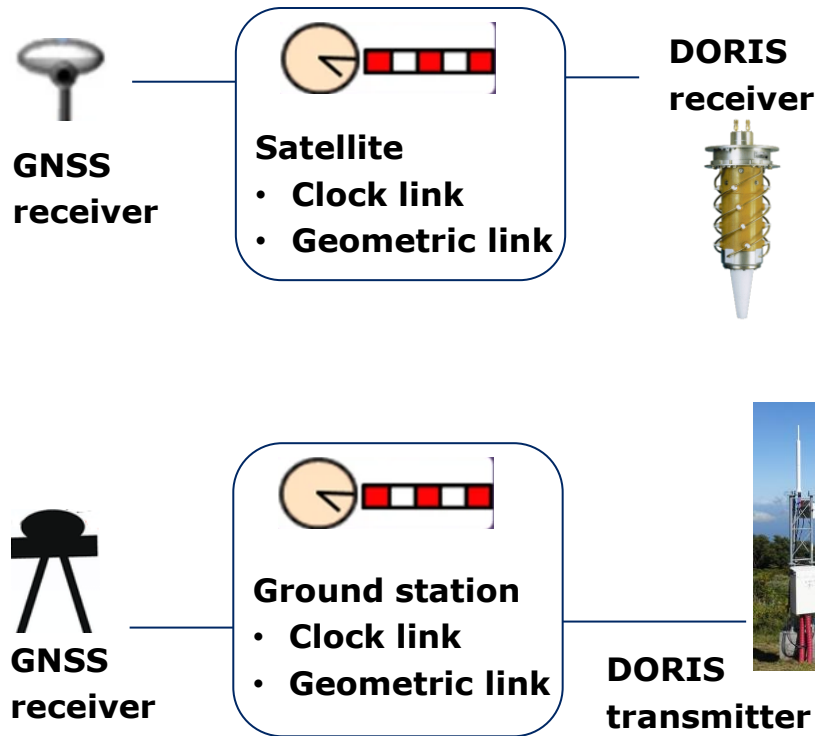
- DORIS and GNSS receiver are linked to the same USO
- E.g. Sentinel 3A, 3B, 6A (MF)

Clock Co-Location on Ground

- Ground clock co-location (REGINA project)



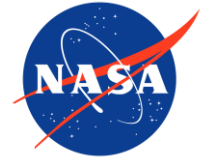
Map of the REGINA network (CNES, 2024)



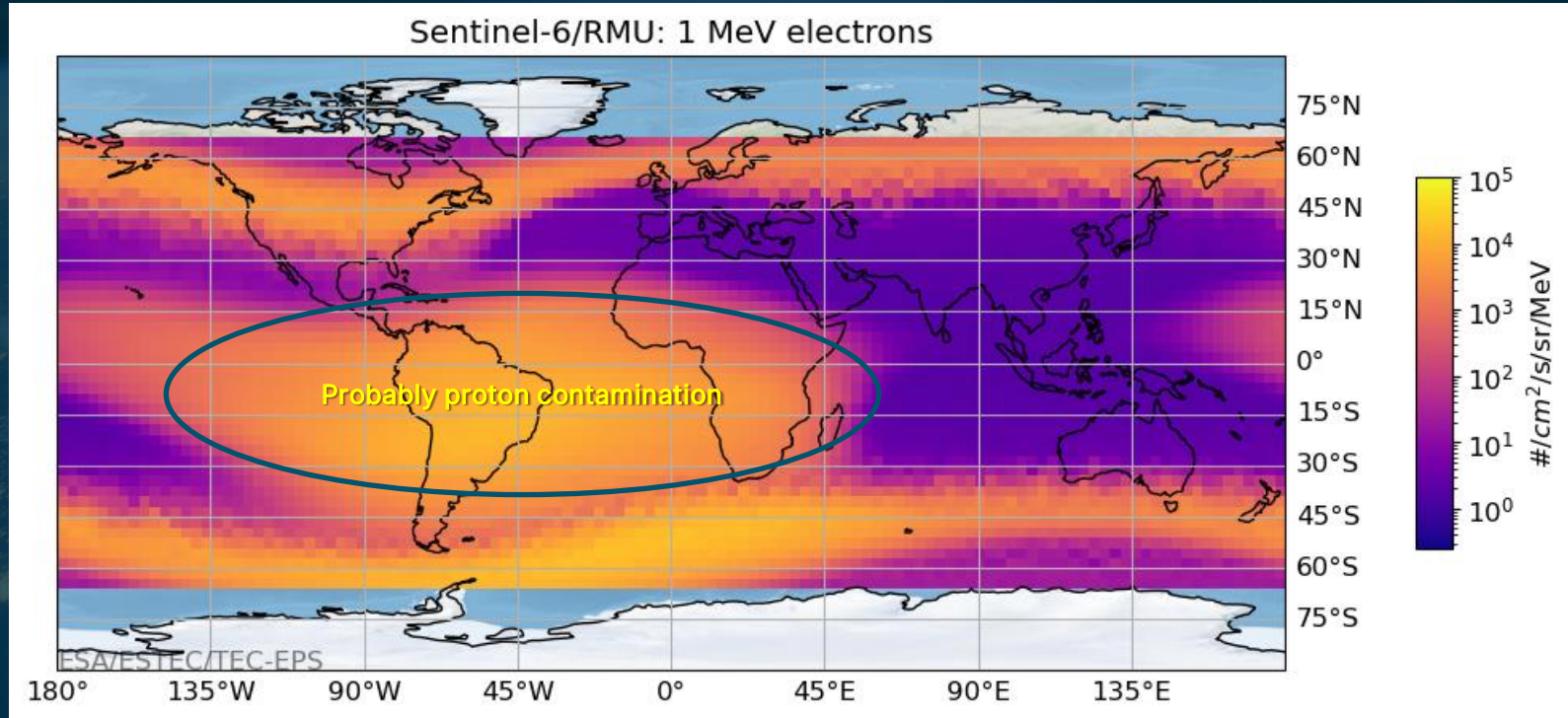
1.2 General

Activities Overview:

- CNES+CLS
 - Clock solution and internal applications
- GFZ
 - Applying external CLK solution
 - Working on own CLK product
- GMV
 - Integrated DORIS processing into FocusPOD
 - Providing clock product
- GOP+TUM
 - DFG project on DORIS clocks
 - Master's thesis on DORIS clocks in cooperation with DTU
- PosiTim
 - Applying external clock solution



The Data for 2024 – 1 MeV electrons

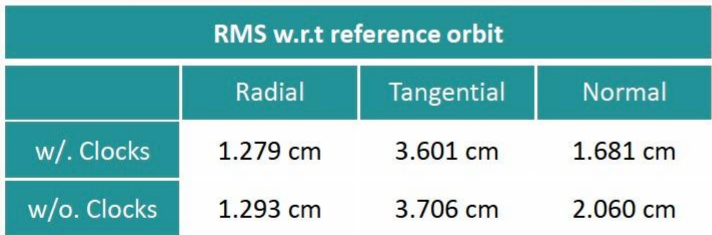


1.3 Contributions

- Conference contributions
 - CNES/CLS presentation at IDS workshop 2024
 - CNES/CLS poster at EGU 2025
 - WG joint abstract submitted to REFAG 2026
- CPOD QWG meeting
 - Joint presentation on the use of clock products

2.1 CNES / CLS

Sentinel-3A



Also improvement w.r.t. usual DORIS dynamic orbit



Station positions

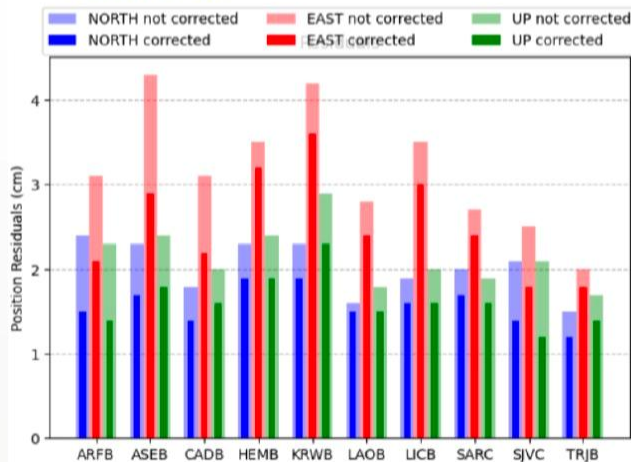
CNES/CLS IDS Analysis Center study – EGU2025

■ Positioning Residual STD

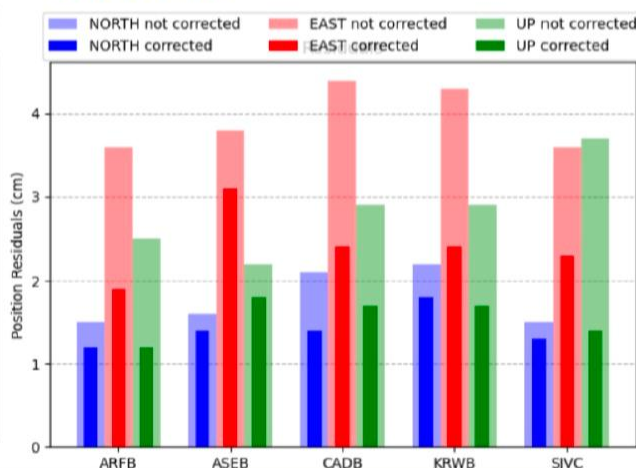
Time series of DORIS coordinates wo and w correcting the SAA stations.

After removing the long-term trend, we compare the residual noise levels (STD) in NEU components.

Sentinel-6A



Sentinel-3A



[Capdeville, H., Mezerette, A., Gravalon, T., Lemoine, J.-M., Moyard, J., Mercier, F., and Couhert, A.: Analyzing the Impact of GPS Clock as the modelled DORIS USO on Station Position Estimation for Sentinel Satellites, EGU General Assembly 2025, Vienna, Austria, 27 Apr–2 May 2025, EGU25-11124, <https://doi.org/10.5194/egusphere-egu25-11124>, 2025.]

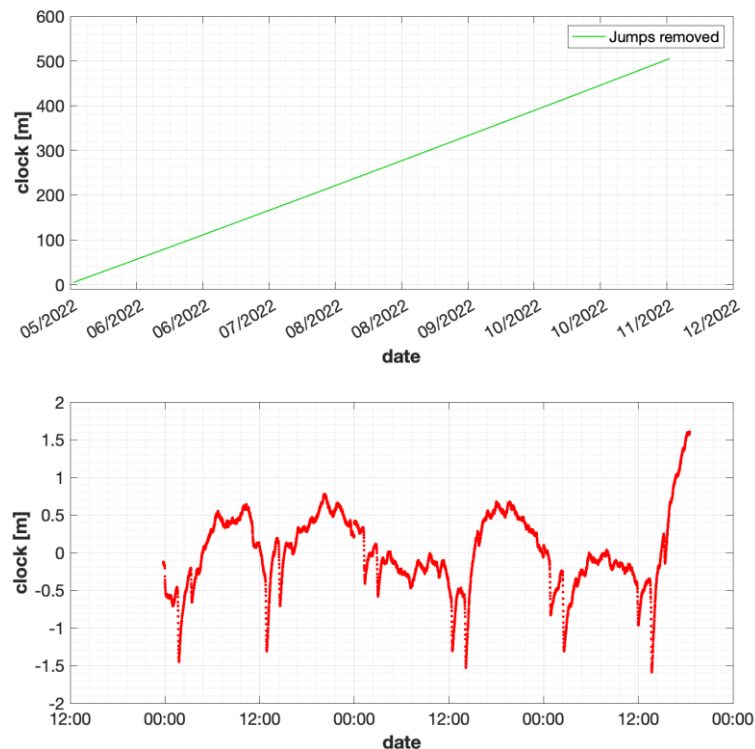
2021.0-2023.9 period

Improvement more important than on the orbits aspect !

2.2 GFZ

2.2.1 Clocks

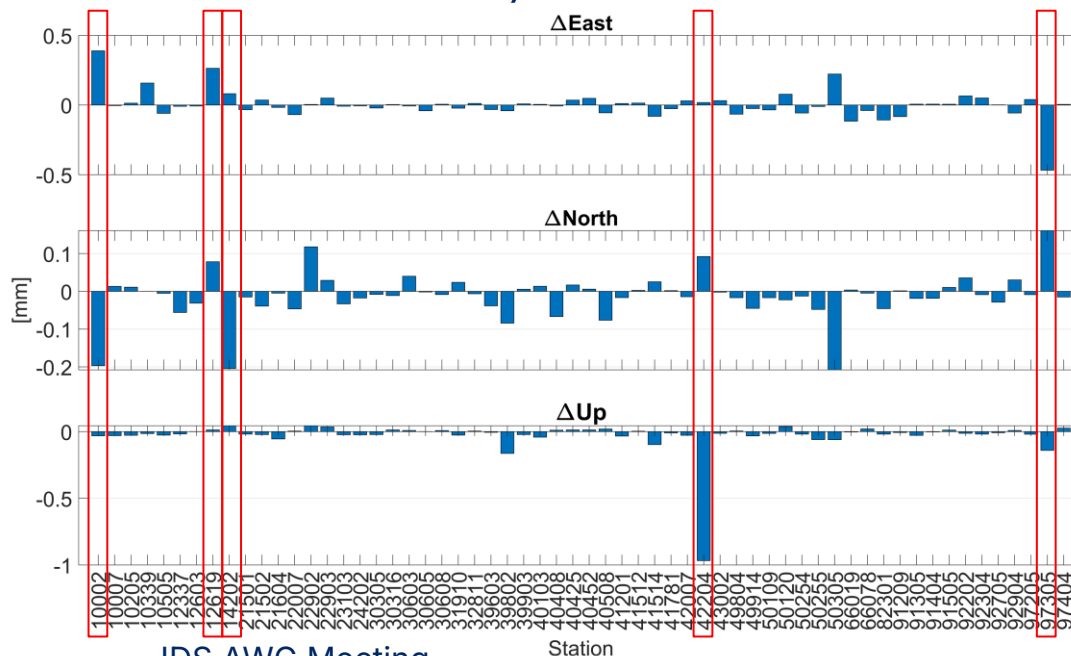
- Raw clock from CNES/CLS
- 10 ms clock jumps are corrected
- Daily third degree polynomial fit is removed
 - The timestamp of DORIS RINEX is edited by this correction



2.2.2 Station RMS

Estimation of station coordinates:

- Differences between mean RMS of station coordinate correction to a priori (reference solution vs. solution with corrected clock)
- 10002: Grasse
- 12619 : Gavdos
- 14202: Wettzell
- 42204: Arequipa
- 97305: Kourou



2.3 PosiTim

2.3.1 DORIS processing in NAPEOS

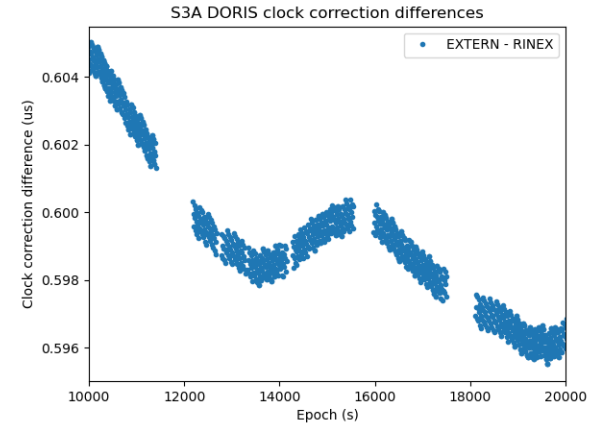
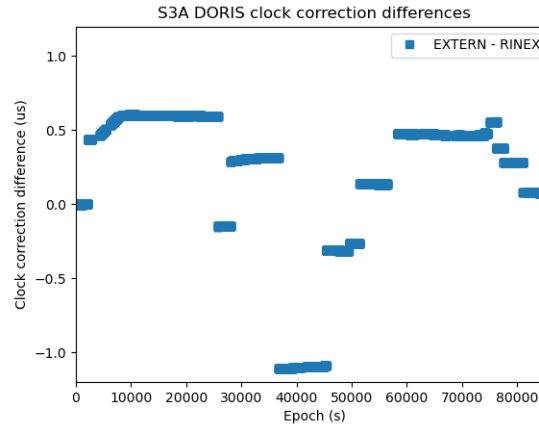
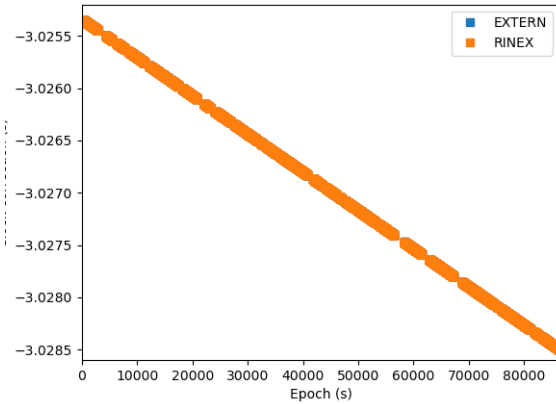
- Carrier phase observations from DORIS RINEX files are converted into Doppler observations, which are used in the orbit determination process (heritage from DORIS 2.2 observation files)
- The use of an external clock product impacts two things:
 - Receiver clock to get the exact measurement epochs
 - Frequency offset to get the proper frequency of the receiver
- Alignment of external clock corrections clk_{ext}
$$clk(t) = clk_{ext}(t) - clk_{ext}(t_{ref}) + clk_{RNX}(t_{ref})$$

=> is this correct?
- Calculation of the frequency offset based on clk_{ext}
 - Polynomial fit (4th order) to values of clk_{ext}
 - Frequency offset is first derivative of this polynomial

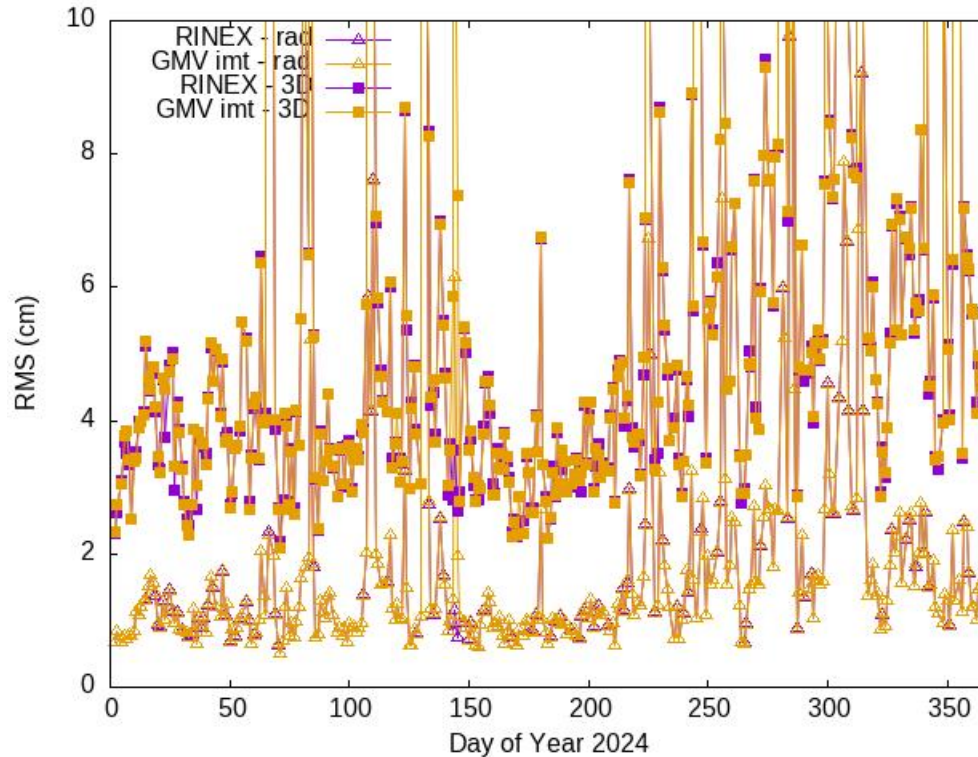
2.3.2 Clock corrections DORIS RINEX vs. external – S3A

2 Jan 2024

S3A DORIS clock corrections



2.3.3 S3A orbit comparisons to RSR combined orbit



- Sentinel-3A orbit comparison of DORIS-derived orbits to RSR#33 combined orbit
 - RINEX => clock taken from entry in DORIS RINEX files
 - GMV int => clock taken from external clock file (GMV int)
- ⇒ Similar performance of both orbit solutions
- ⇒ Several problem days with external clock file

2.3.4 Statistics of comparison to RSR combined orbit

Mean RMS (cm) of orbit comparison to RSR combined orbit – maneuver + clock problem days excluded

Solution	Radial	Along-track	Cross-track	3D
S-3A RINEX	1.35	3.60	2.00	4.42
S-3A GMV imt	1.36	3.62	2.02	4.45
S-3B RINEX	1.28	3.65	2.09	4.48
S-3B GMV imt	1.29	3.67	2.11	4.52
S-6A RINEX	0.80	2.54	2.61	3.82
S-6A imt	0.80	2.55	2.66	3.86

- Similar performance of orbits generated with external clocks compared to RSR combined orbits

4 Objectives

- **DORIS clock co-location**
 1. Create test clock series for testing of processing
 2. Modify DORIS data processing tools
 3. Investigate various correction strategies (sampling, smoothing) and run testing campaigns
 4. Create a product to be used by IDS and end users
- **Prepare a recommendation for routine production of the clock products and their archival at the IDS data centers as an official IDS product**
- **Prepare recommendations for future missions concerning DORIS-GNSS clock co-locations**